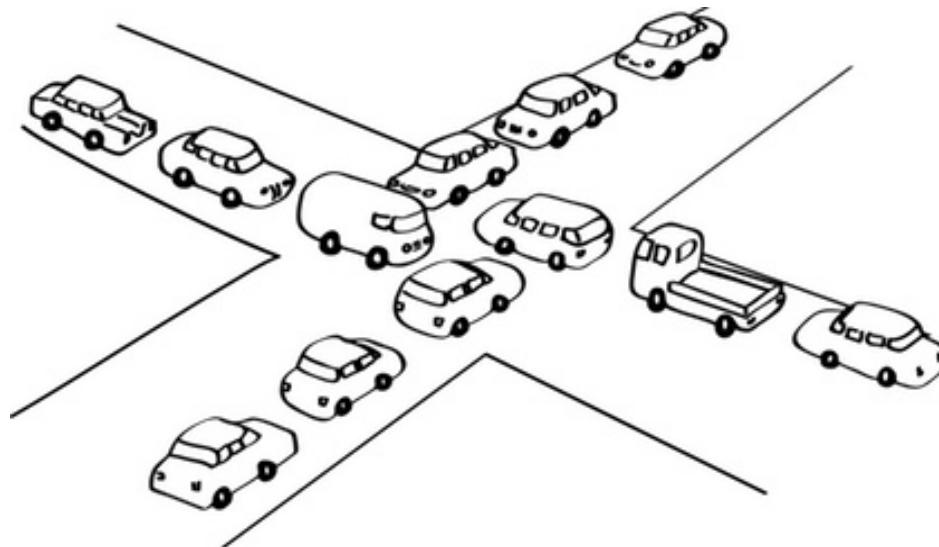


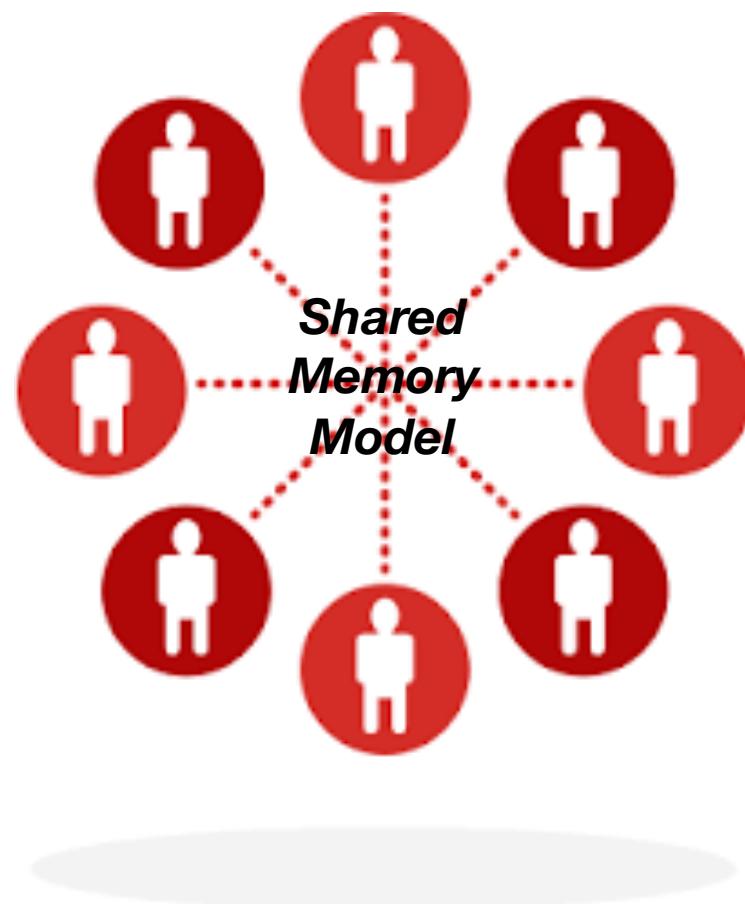
# Go Concurrent Programming



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**QCon2018 Beijing**

# Shared Memory Model



```
class Worker implements Runnable{  
    private volatile boolean isRunning = false;  
    @Override  
    public void run() {  
        while(isRunning) {  
            //do something  
        }  
    }  
}
```

```
Lock lock = ...;  
lock.lock();  
try{  
    //process (thread-safe)  
}catch(Exception ex){  
  
}finally{  
    lock.unlock();  
}
```

# CSP

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## Communicating sequential processes

From Wikipedia, the free encyclopedia

In computer science, **communicating sequential processes (CSP)** is a [formal language](#) for describing [patterns of interaction](#) in [concurrent systems](#).<sup>[1]</sup> It is a member of the family of mathematical theories of concurrency known as process algebras, or process calculi, based on [message passing](#) via [channels](#). CSP was highly influential in the design of the [occam](#) programming language,<sup>[1][2]</sup> and also influenced the design of programming languages such as [Limbo](#),<sup>[3]</sup> [RaftLib](#), [Go](#)<sup>[4]</sup>, [Crystal](#), and [Clojure](#)'s `core.async`.

CSP was first described in a 1978 paper by Tony Hoare,<sup>[5]</sup> but has since evolved substantially.<sup>[6]</sup> CSP has been practically applied in industry as a tool for [specifying and verifying](#) the concurrent aspects of a variety of different systems, such as the T9000 [Transputer](#),<sup>[7]</sup> as well as a secure ecommerce system.<sup>[8]</sup> The theory of CSP itself is also still the subject of active research, including work to increase its range of practical applicability (e.g., increasing the scale of the systems that can be tractably analyzed).<sup>[9]</sup>

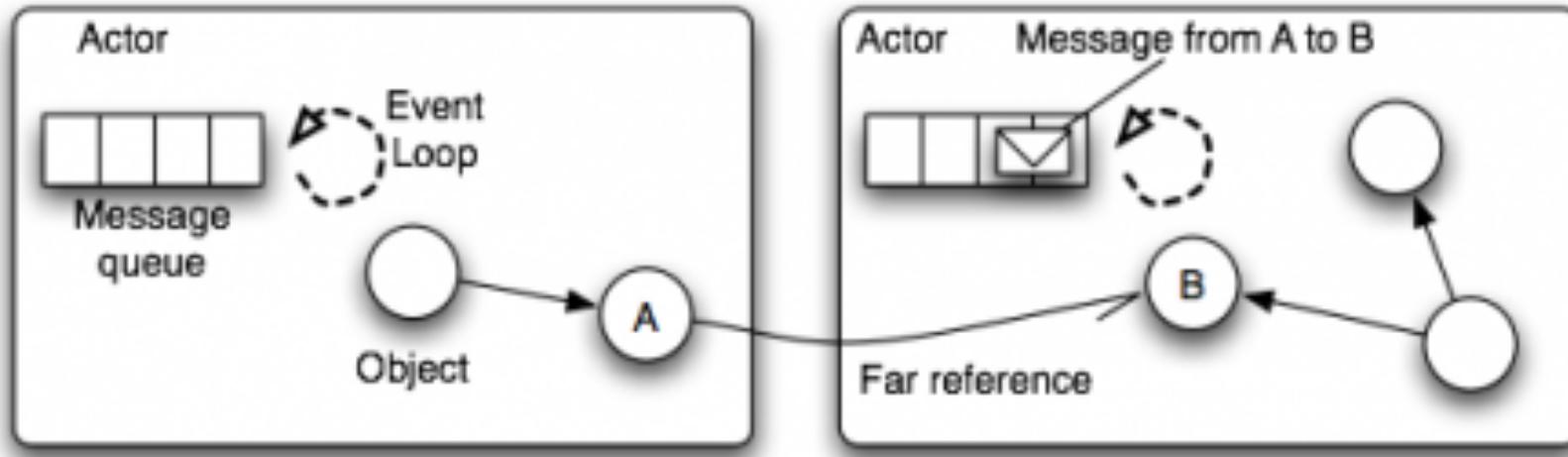
**Contents** [hide]

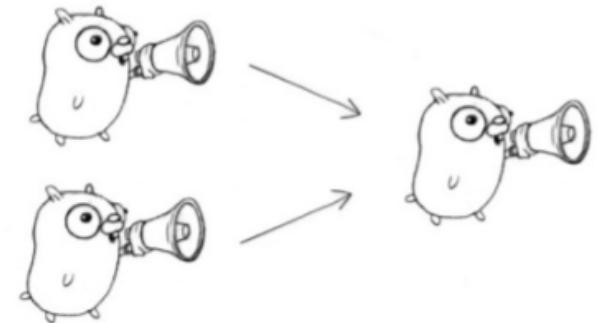
- 1 History
  - 1.1 Applications
- 2 Informal description
  - 2.1 Primitives



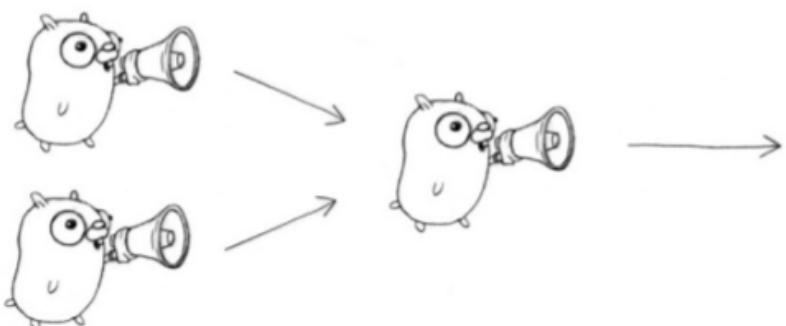
Tony Hoare

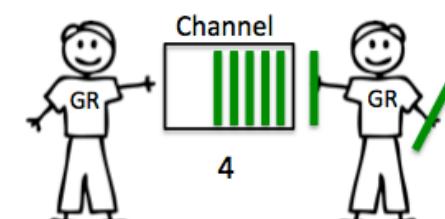
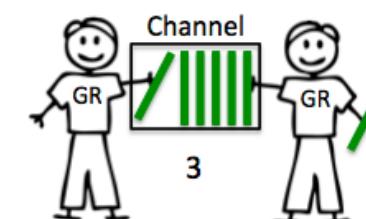
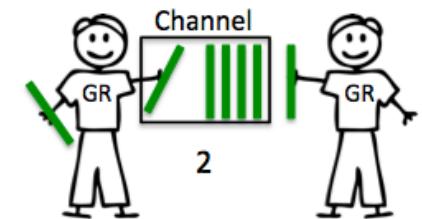
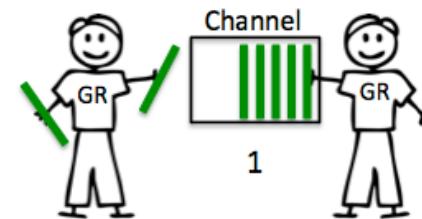
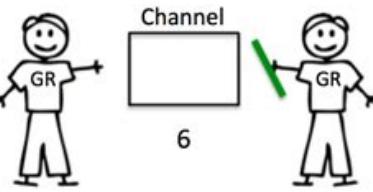
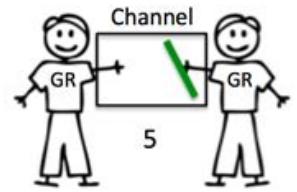
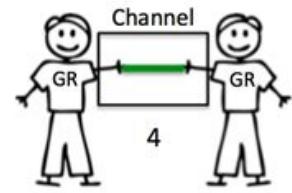
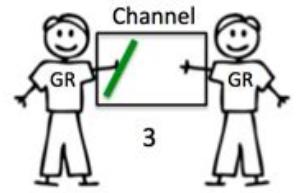
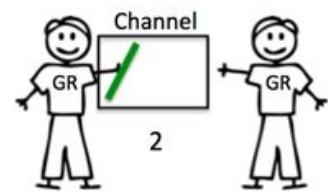
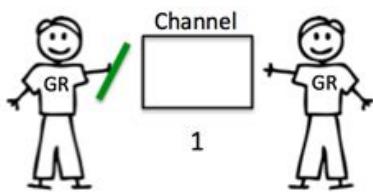
# Actor Model





# Channel





# Nonblocking Call

```
private static FutureTask<String> service() {  
    FutureTask<String> task = new FutureTask<String>(()->"Do something");  
    new Thread(task).start();  
    return task;  
}
```

```
FutureTask<String> ret = service();  
System.out.println("Do something else");  
System.out.println(ret.get());
```

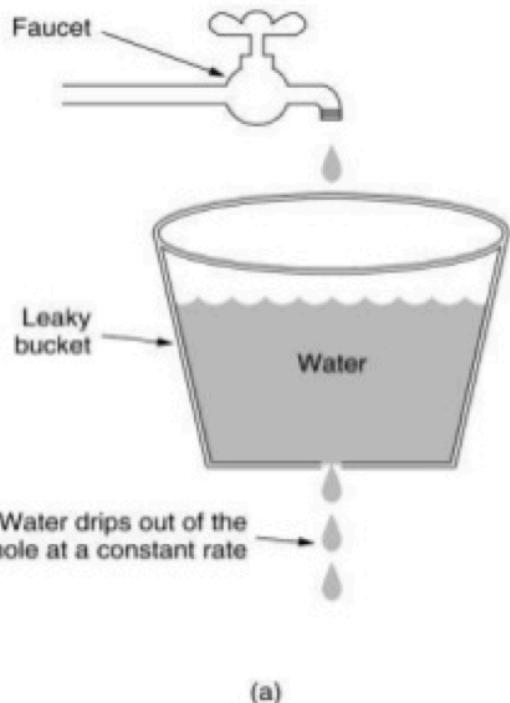
```
func Service() <-chan string {  
    ret := make(chan string)  
    go func() {  
        ret <- "Do something"  
    }()  
    return ret  
}
```

```
func TestService(t *testing.T) {  
    r := Service() //Nonblock call  
    fmt.Println("Do something else") //do something else  
    fmt.Println(<-r) //Waiting for the result  
}
```

# Util Anyone Responses

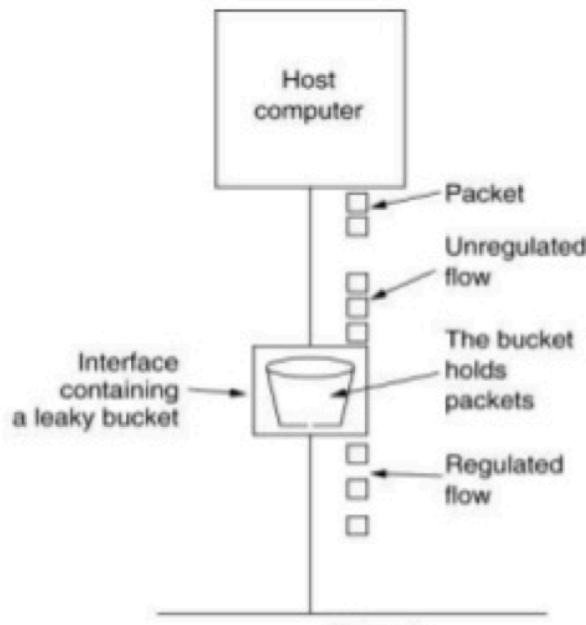
```
func UntilAnyoneResponse(callables []Callable) interface{} {
    ch := make(chan interface{}, len(callables))
    for _, callable := range callables {
        go func(c Callable) {
            ch <- c.Call()
        }(callable)
    }
    return <-ch
}
```

# Rate Limit



(a)

(a) A leaky bucket with water.



(b)

(b) a leaky bucket with packets.

```
func CreateTokenBucket(sizeOfBucket int, numOfTokens int,
    tokenFillingInterval time.Duration) chan time.Time {
    bucket := make(chan time.Time, sizeOfBucket)
    //fill the bucket firstly
    for j := 0; j < sizeOfBucket; j++ {
        bucket <- time.Now()
    }
    go func() {
        for t := range time.Tick(tokenFillingInterval) {
            for i := 0; i < numOfTokens; i++ {
                bucket <- t
            }
        }
    }()
    return bucket
}
```

```
func GetToken(tokenBucket chan time.Time,
    timeout time.Duration) (time.Time, error) {
    var token time.Time

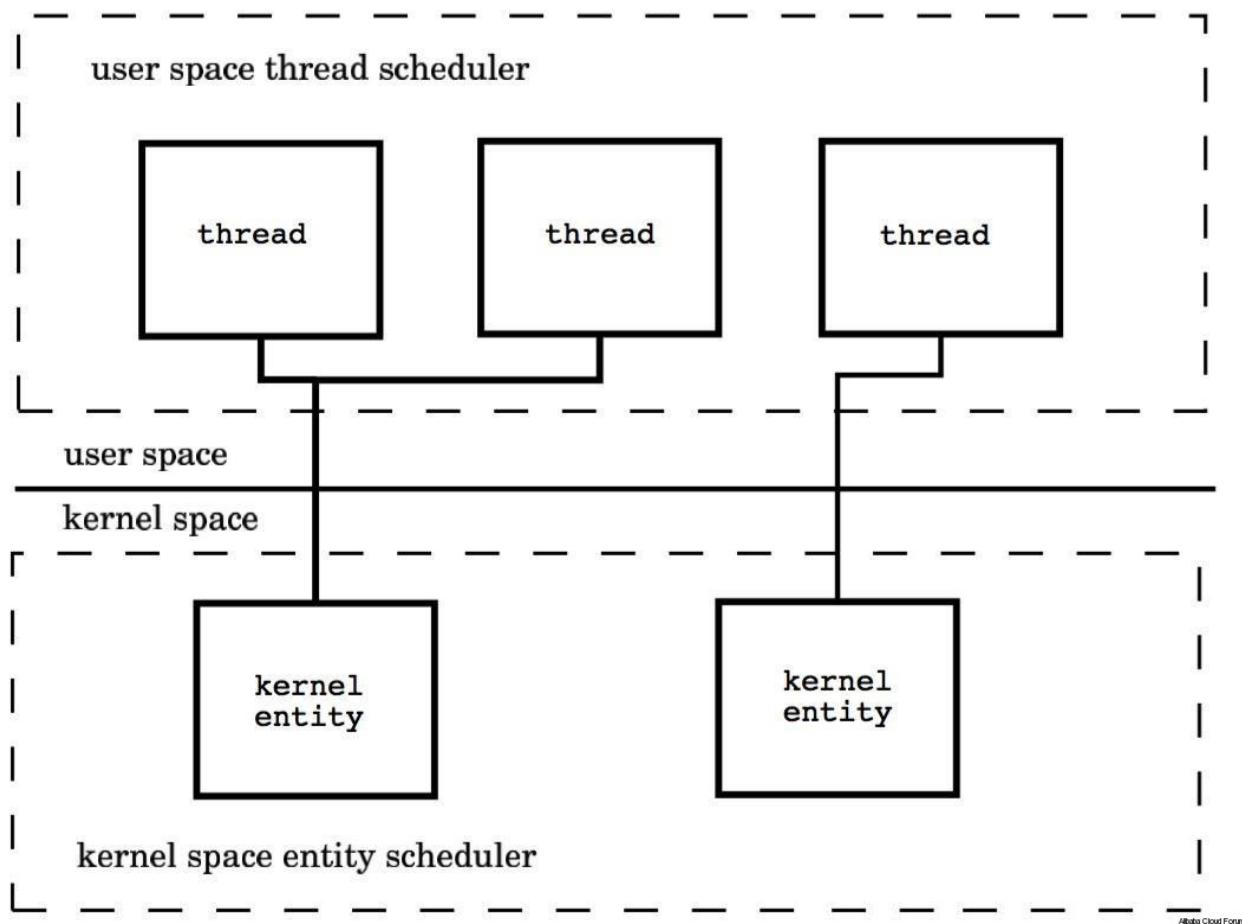
    if timeout != 0 {
        select {
        case token = <-tokenBucket:
            return token, nil
        case <-time.After(timeout):
            return token, errors.New("Failed to get token for time out")
        }
    }
    token = <-tokenBucket
    return token, nil
}
```

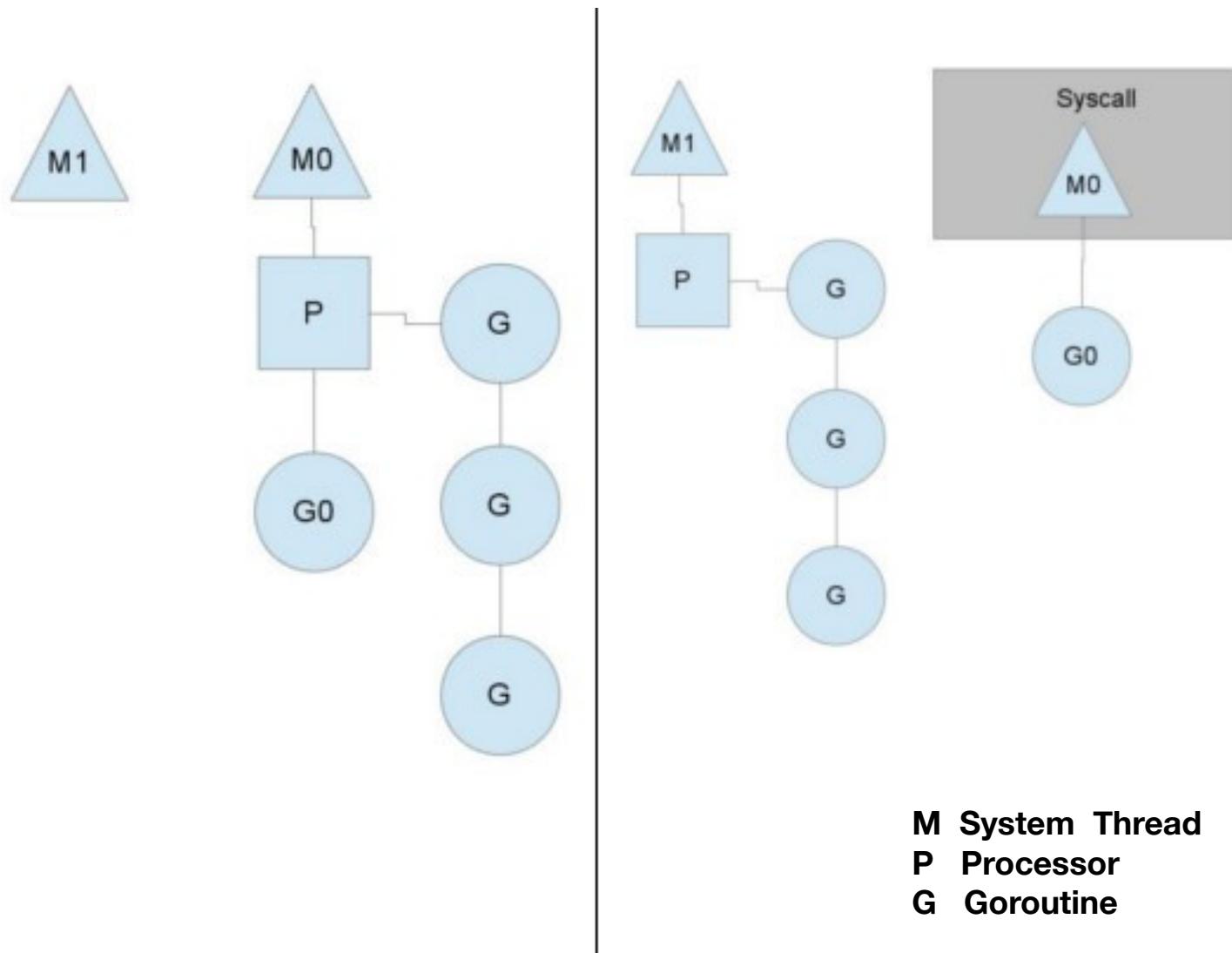
# Traps

```
func f1() {
    var wg sync.WaitGroup
    for i := 0; i < 10; i++ {
        wg.Add(1)
        go func() {
            fmt.Println(i)
            wg.Done()
        }()
    }
    wg.Wait()
}
```

```
func f2() {
    var wg sync.WaitGroup
    for i := 0; i < 10; i++ {
        wg.Add(1)
        go func(p int) {
            fmt.Println(p)
            wg.Done()
        }(i)
    }
    wg.Wait()
}
```

# Goroutine Leak





```
func UntilAnyoneResponse(callables []Callable) interface{} {
    ch := make(chan interface{})
    for _, callable := range callables {
        go func(c Callable) {
            ch <- c.Call()
        }(callable)
    }
    return <-ch
}
```

```
func UntilAnyoneResponse(callables []Callable) interface{} {
    ch := make(chan interface{}, len(callables))
    for _, callable := range callables {
        go func(c Callable) {
            ch <- c.Call()
        }(callable)
    }
    return <-ch
}
```

```
runtime.NumGoroutine()
```



*You might be surprised!*

# Recipes

- Rate Limit
- Timeout/Circuit Break
- Number of Goroutine Limit

# Cancellation

```
class Worker implements Runnable{  
    private volatile boolean isRunning = false;  
    @Override  
    public void run() {  
        while(isRunning) {  
            //do something  
        }  
    }  
}
```

# Broadcast by Channel

```
func isCancelled(cancelChan chan struct{}) bool {  
    select {  
        case <-cancelChan:  
            return true  
        default:  
            return false  
    }  
}
```

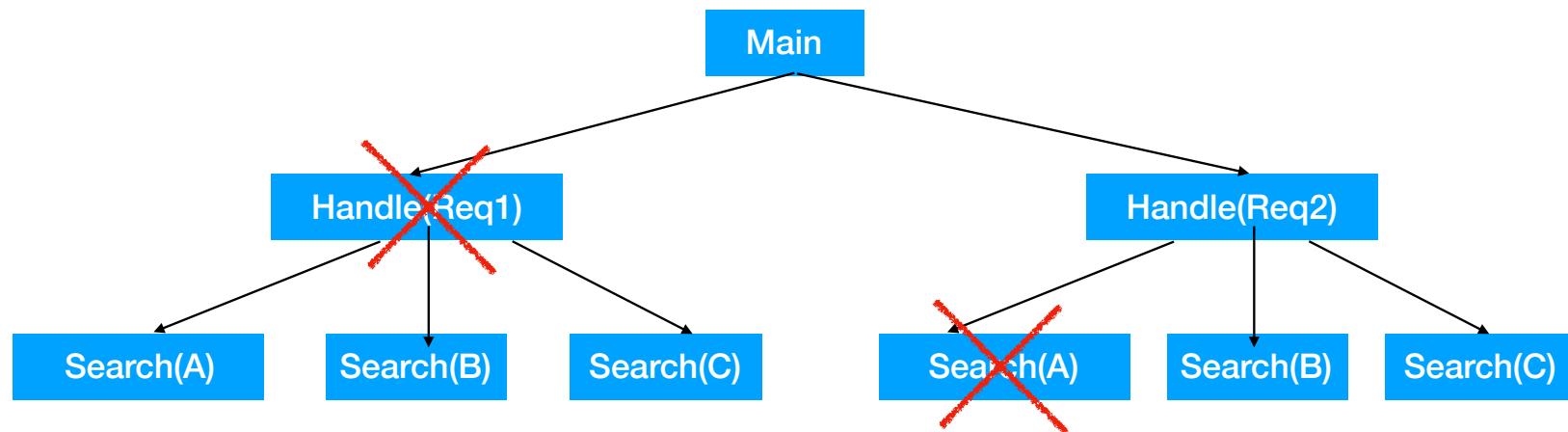
# Broadcast by Channel

```
func cancel_1(cancelChan chan struct{}) {  
    cancelChan <- struct{}{}  
}
```

# Broadcast by Channel

```
func cancel_2(cancelChan chan struct{}) {
    fmt.Println("Cancelled!")
    close(cancelChan)
}
```

# Context



```
func main() {
    ctx, cancel := context.WithCancel(context.Background())
    go func(ctx context.Context) {
        for {
            select {
            case <-ctx.Done():
                fmt.Println("Stop processing ...")
                return
            default:
                fmt.Println("Running...")
                time.Sleep(2 * time.Second)
            }
        }
    }(ctx)

    time.Sleep(10 * time.Second)
    fmt.Println("Done. Stop it!")
    cancel()
}

...
```

# Lock Free

```
func lockFreeAccess() {
    var wg sync.WaitGroup
    wg.Add(NUM_OF_READER)
    for i := 0; i < NUM_OF_READER; i++ {
        go func() {
            for j := 0; j < READ_TIMES; j++ {
                _, err := cache["a"]
                if !err {
                    fmt.Println("Nothing")
                }
            }
            wg.Done()
        }()
    }
    wg.Wait()
}
```

**0.03 ns/op**

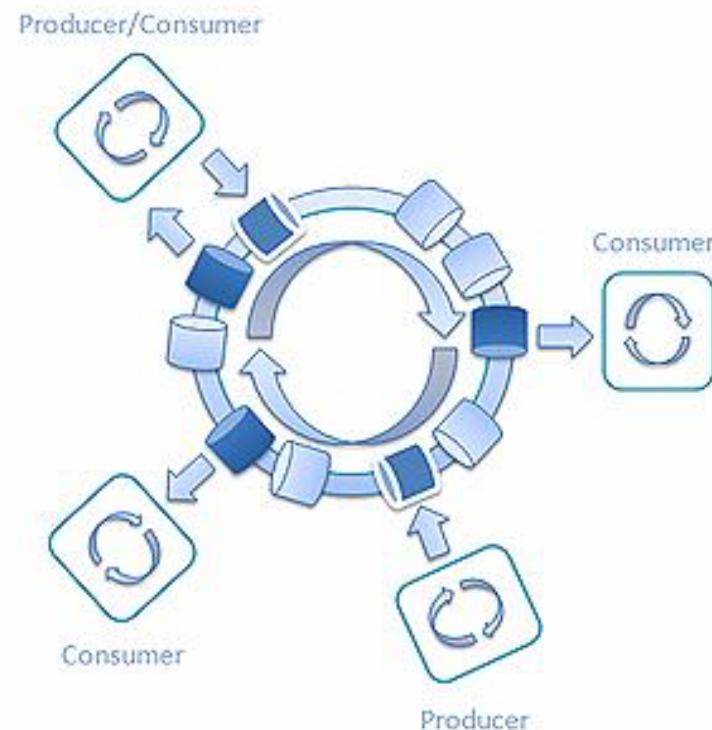
```
func lockAccess() {
    var wg sync.WaitGroup
    wg.Add(NUM_OF_READER)
    m := new(sync.RWMutex)
    for i := 0; i < NUM_OF_READER; i++ {
        go func() {
            for j := 0; j < READ_TIMES; j++ {
                m.RLock()
                _, err := cache["a"]
                if !err {
                    fmt.Println("Nothing")
                }
                m.RUnlock()
            }
            wg.Done()
        }()
    }
    wg.Wait()
}
```

**0.57 ns/op**

Method	Time (ms)
Single thread	300
Single thread with CAS	5,700
Single thread with lock	10,000
Single thread with volatile write	4,700
Two threads with CAS	30,000
Two threads with lock	224,000

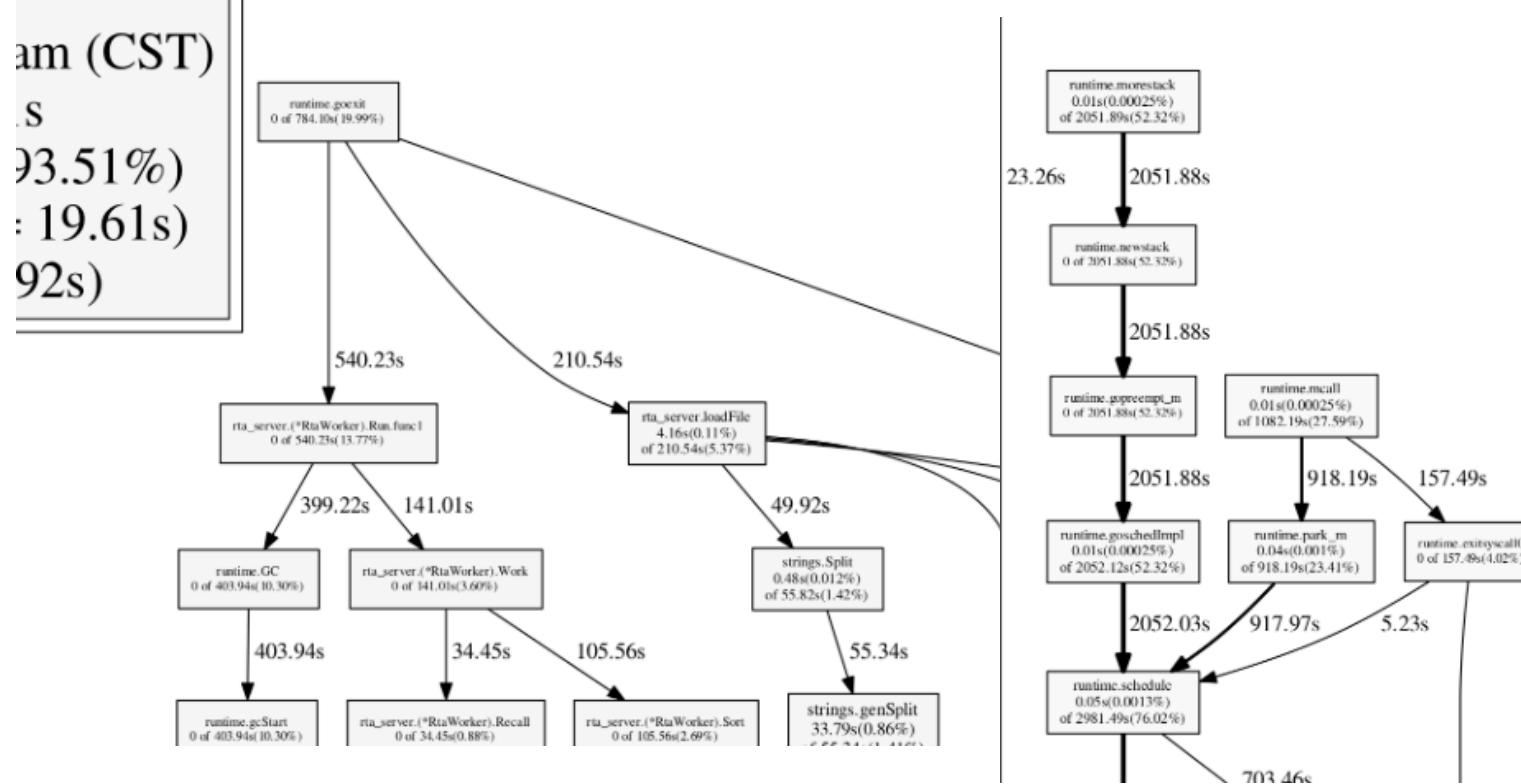
**2.5G 6 Cores  
64 bit integer self-increment  
(500M times)**

# Disruptor



# Key Points

- Continuous Memory
- Avoid of the high cost operations (memory allocation, GC)
- Lock Free
- Leverage modern CPU
  - Cache-line/False Share
  - Memory Barrier



# Difference

*The master has failed more times than the beginner has tried.*