



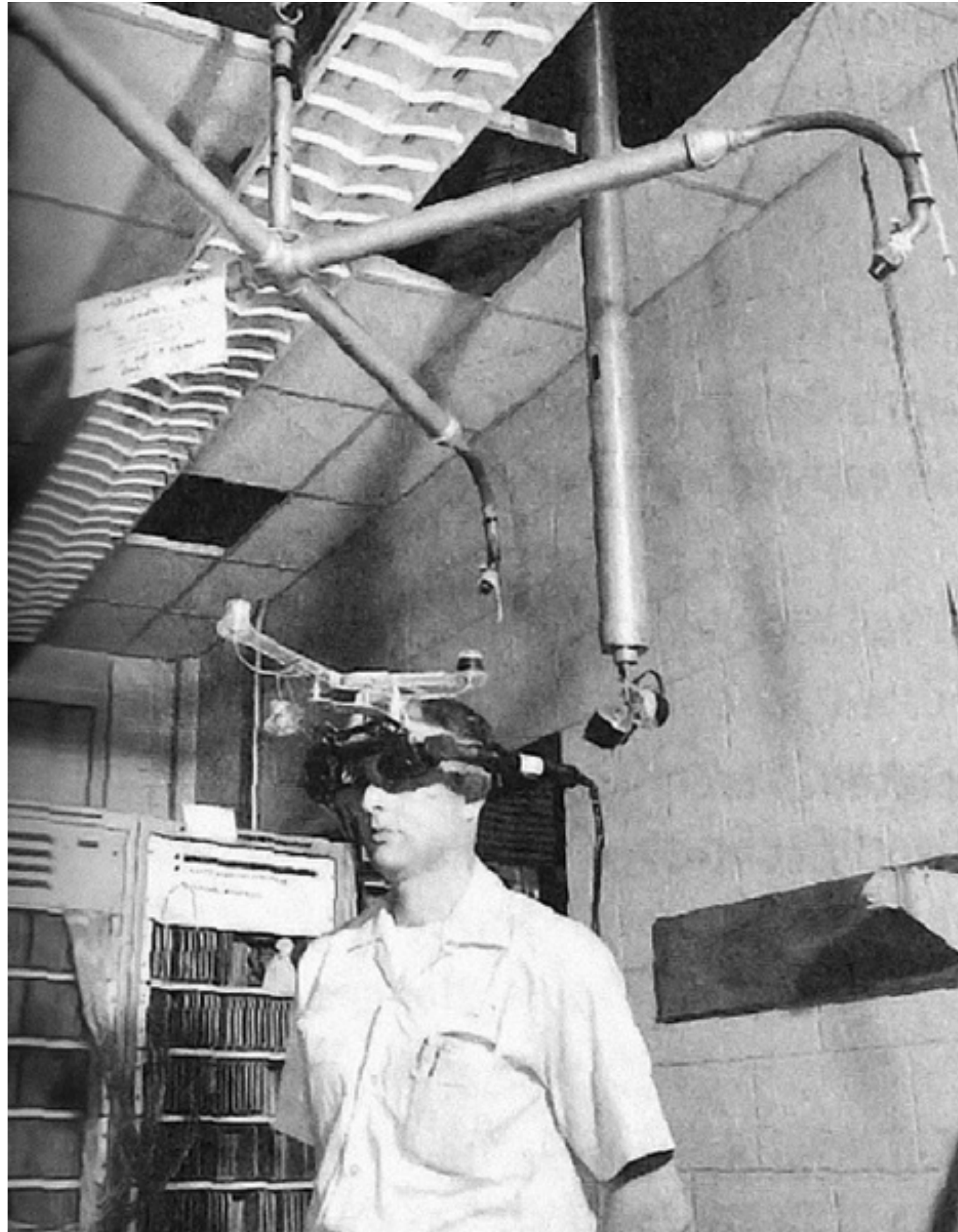
QCon 全球软件开发大会
INTERNATIONAL SOFTWARE
DEVELOPMENT CONFERENCE

BEIJING 2018

Future Directions for Augmented Reality

Mark Billinghurst

1968 – Sutherland/Sproull's HMD





<https://www.youtube.com/watch?v=NtwZXGprxag>

Star Wars - 1977



Augmented Reality

- Combines Real and Virtual Images
 - Both can be seen at the same time
- Interactive in real-time
 - The virtual content can be interacted with
- Registered in 3D
 - Virtual objects appear fixed in space

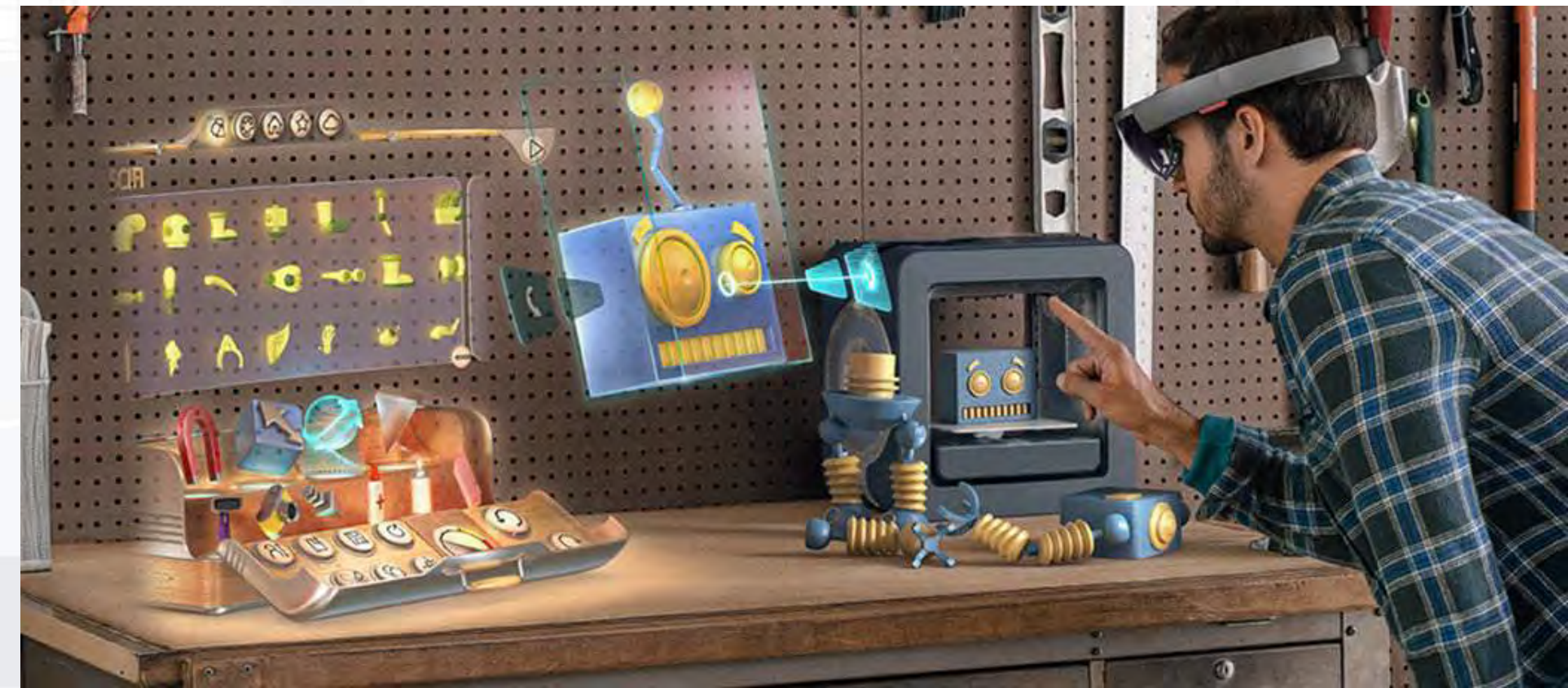
Azuma, R. T. (1997). A survey of augmented reality. *Presence*, 6(4), 355-385.

2008 - CNN



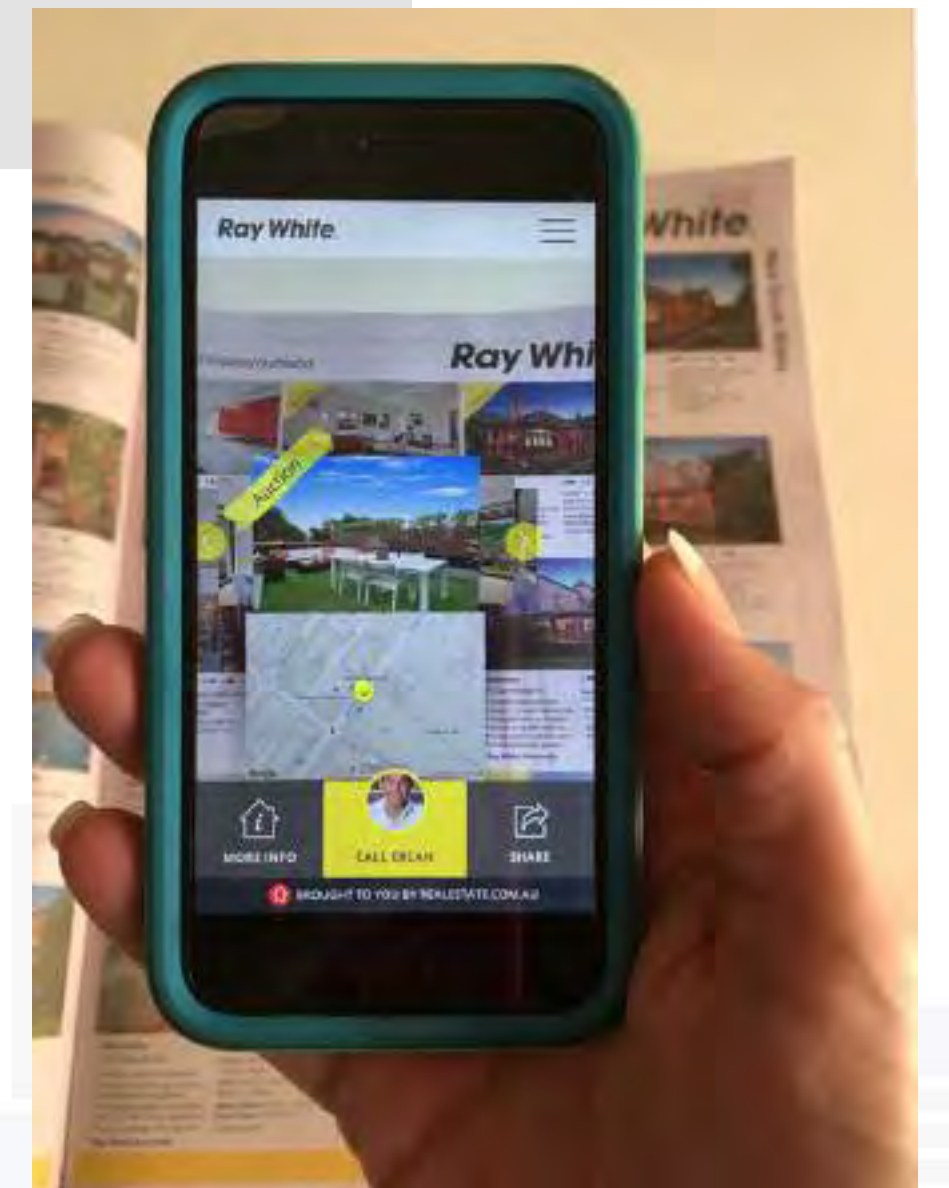
https://www.youtube.com/watch?v=v7fQ_EsMJMs

Augmented Reality Applications

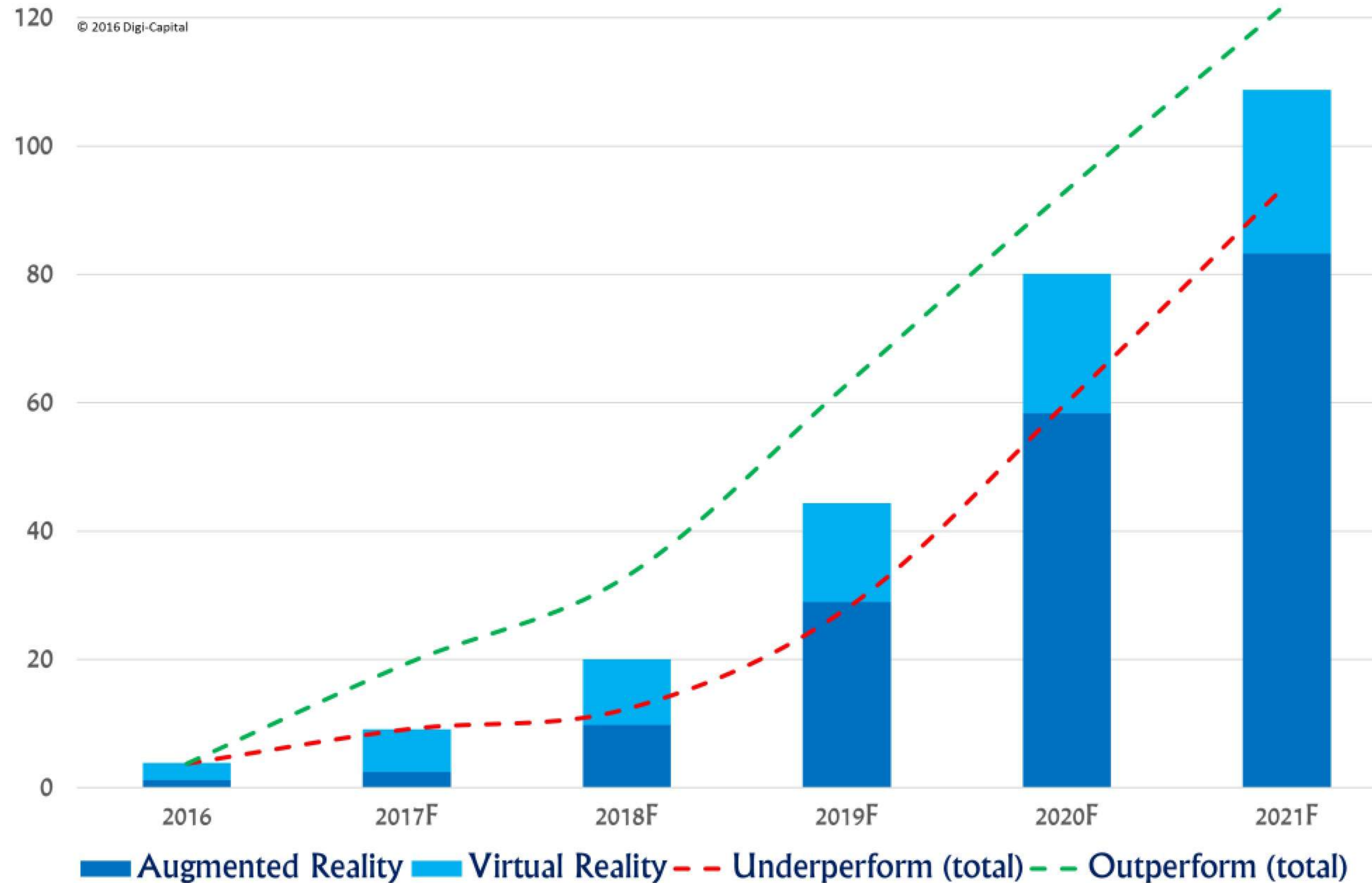


Augmented Reality in 2018

- Large growing market
 - \$1.2B USD in 2016, \$3B in 2017
- Many available devices
 - HMD, phones, tablets, HUDs
- Robust developer tools
 - Vuforia, ARToolKit, Unity, Wikitude, etc
- Large number of applications
 - > 250K developers, > 100K mobile apps
- Strong research/business communities
 - ISMAR, AWE conferences, AugmentedReality.org, etc



AR Revenue Projections



- > \$80Billion by 2021, > 3x VR Revenue (Digi-Capital)

Future directions



• Combines Real and Virtual Images

Key Enabling Technologies

Display Technology

→
• Interactive in real-time

→
Int

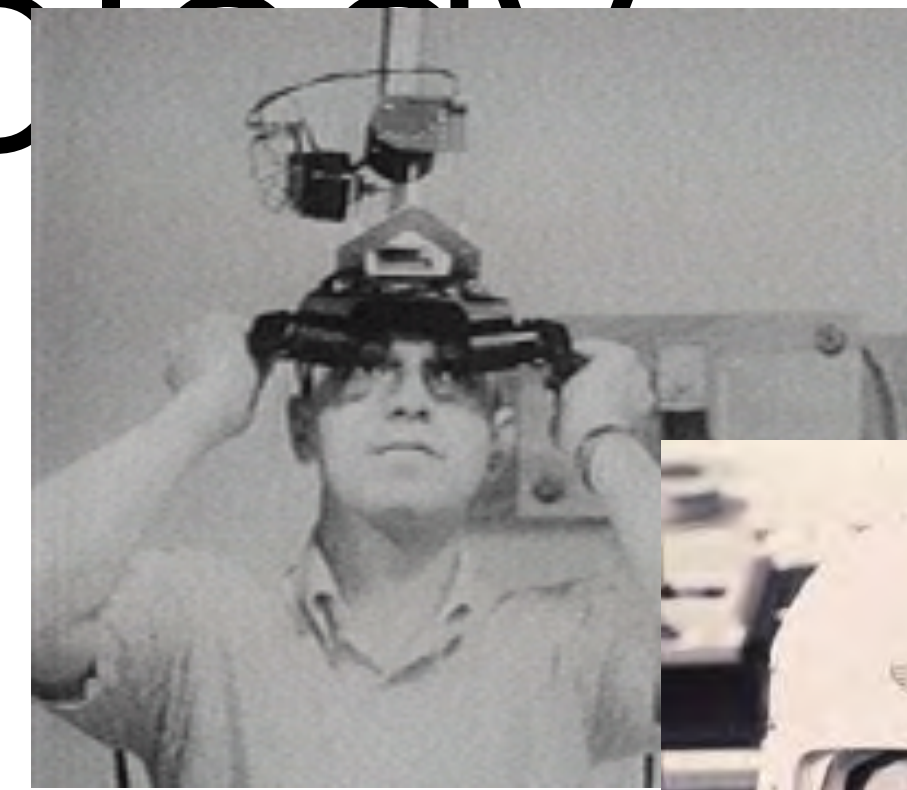
• Registered in 3D

→
T

Display Technology

- Past

- Bulky Head mounted displays



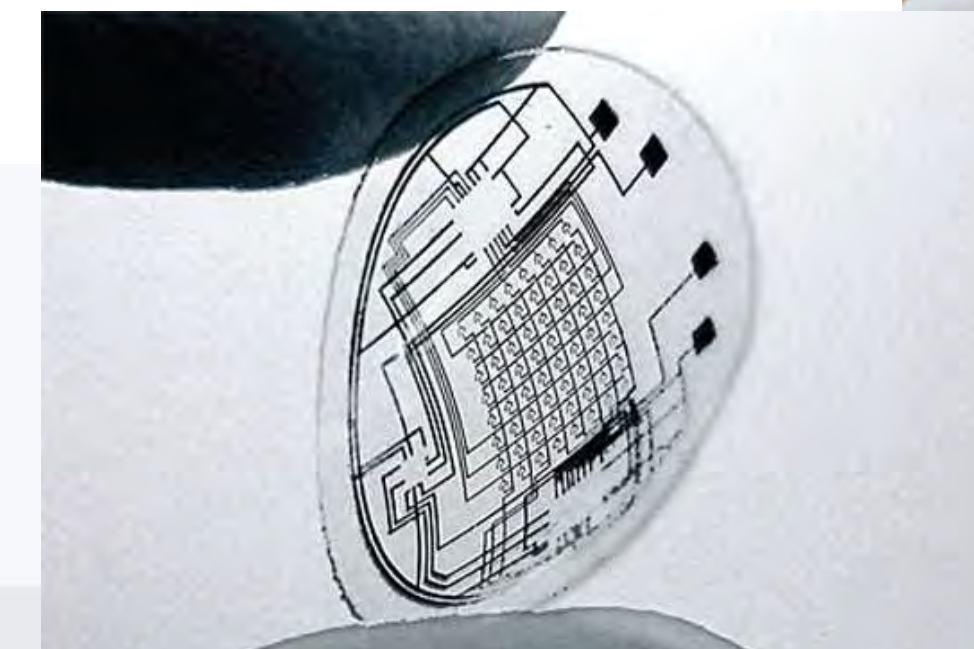
- Current

- Handheld, lightweight head mounted



- Future

- Projected AR
- Wide FOV see through
- Retinal displays
- Contact lens



Wide FOV See-Through (3+ years)

- Waveguide techniques
 - Thin, wider FOV
 - Socially acceptable

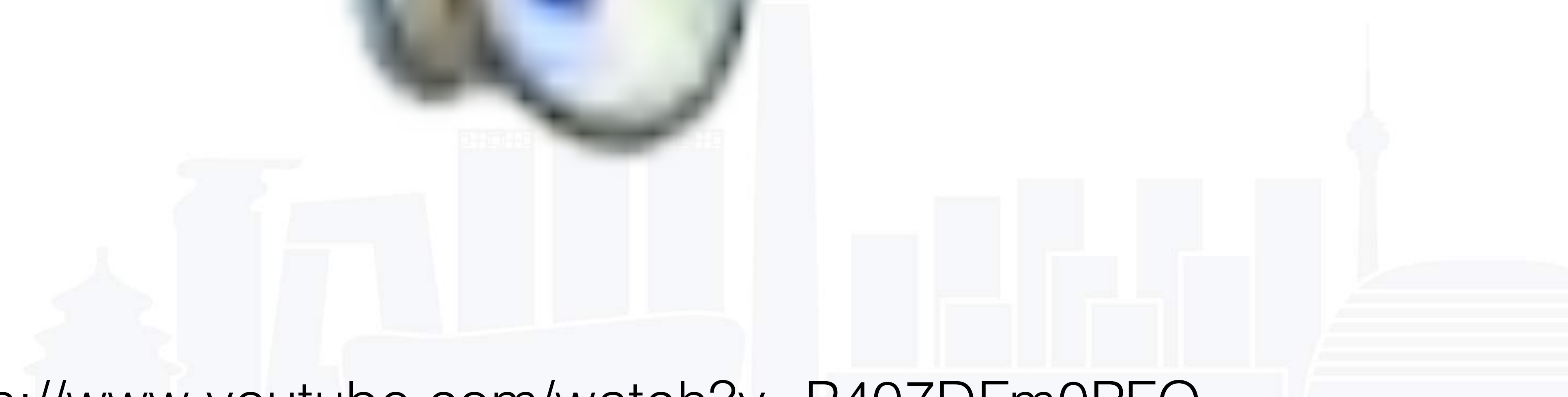


Lumus DK40

- Pinlight Displays
 - LCD panel + point light sources
 - 110 degree FOV



Maimone, A., Lanman, D., Rathinavel, K., Keller, K., Luebke, D., & Fuchs, H. (2014). Pinlight displays: wide field of view augmented reality eyeglasses using defocused point light sources. In *ACM SIGGRAPH 2014 Emerging Technologies* (p. 20). ACM.

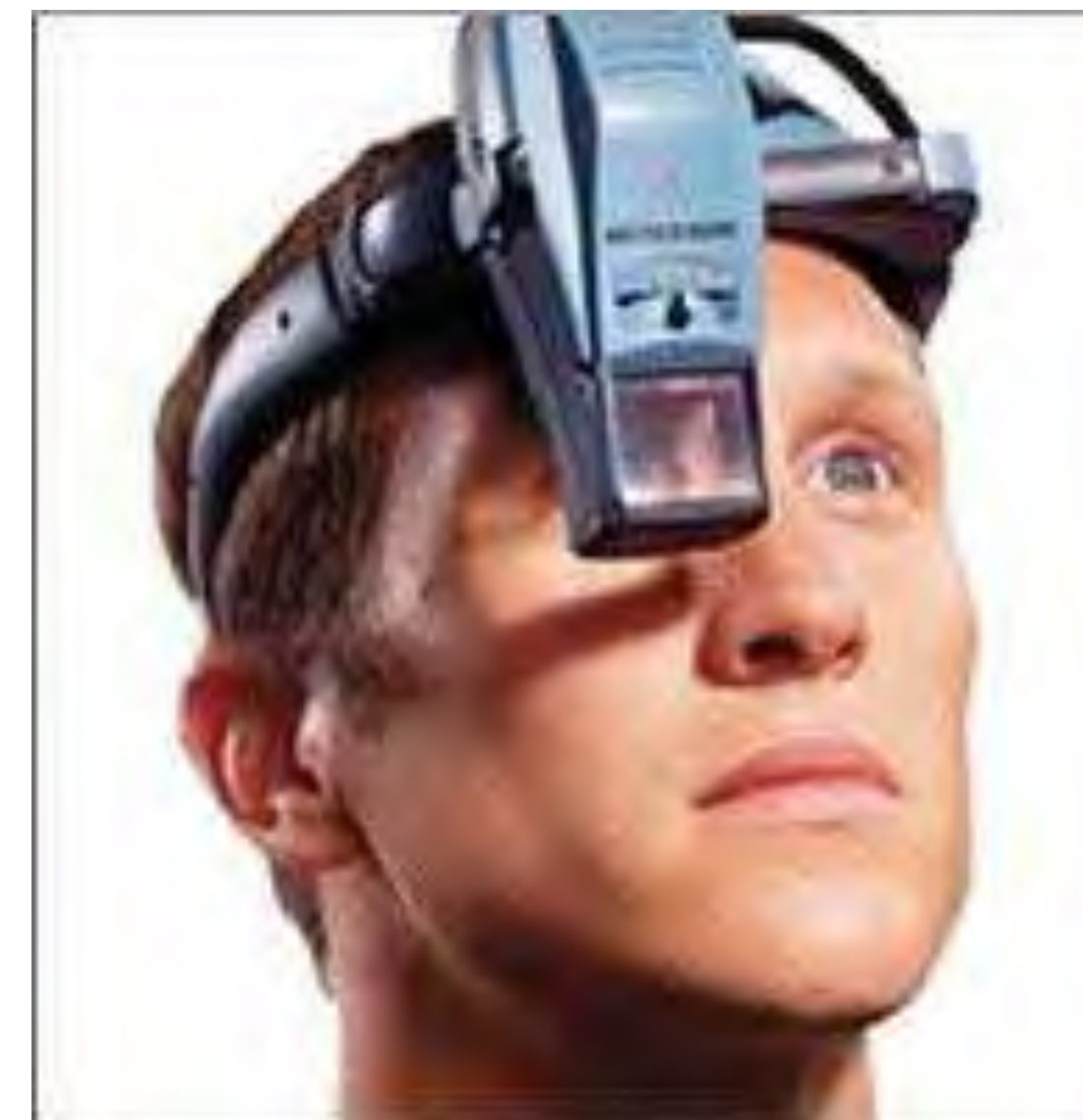


<https://www.youtube.com/watch?v=P407DFm0PFQ>

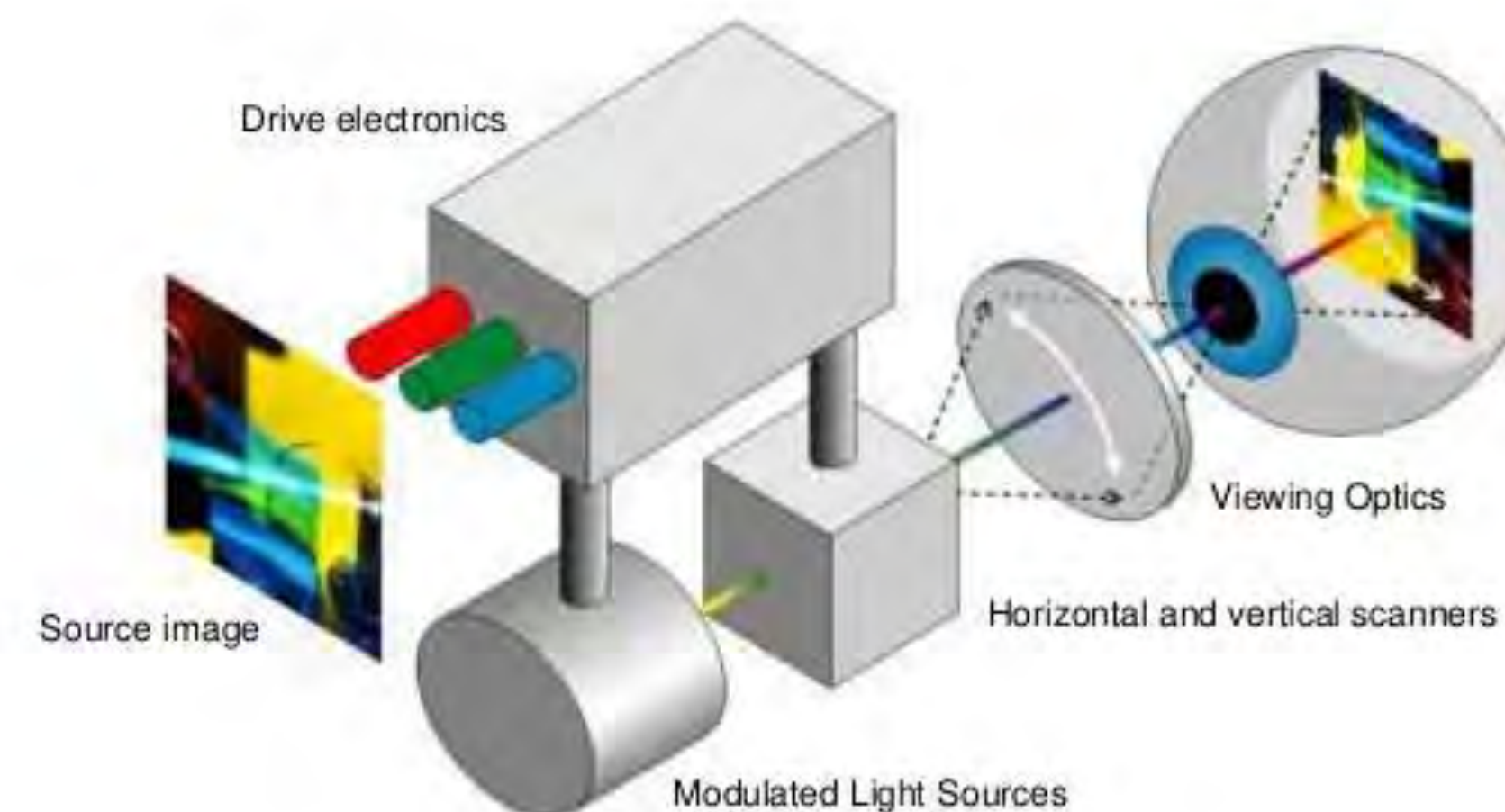
- Photons scanned into eye

Retinal Displays (5+ years)

- Infinite depth of field
- Bright outdoor performance
- Overcome visual defects
- True 3D stereo with depth modulation



- Microvision (1993-)
- Head mounted monochrome

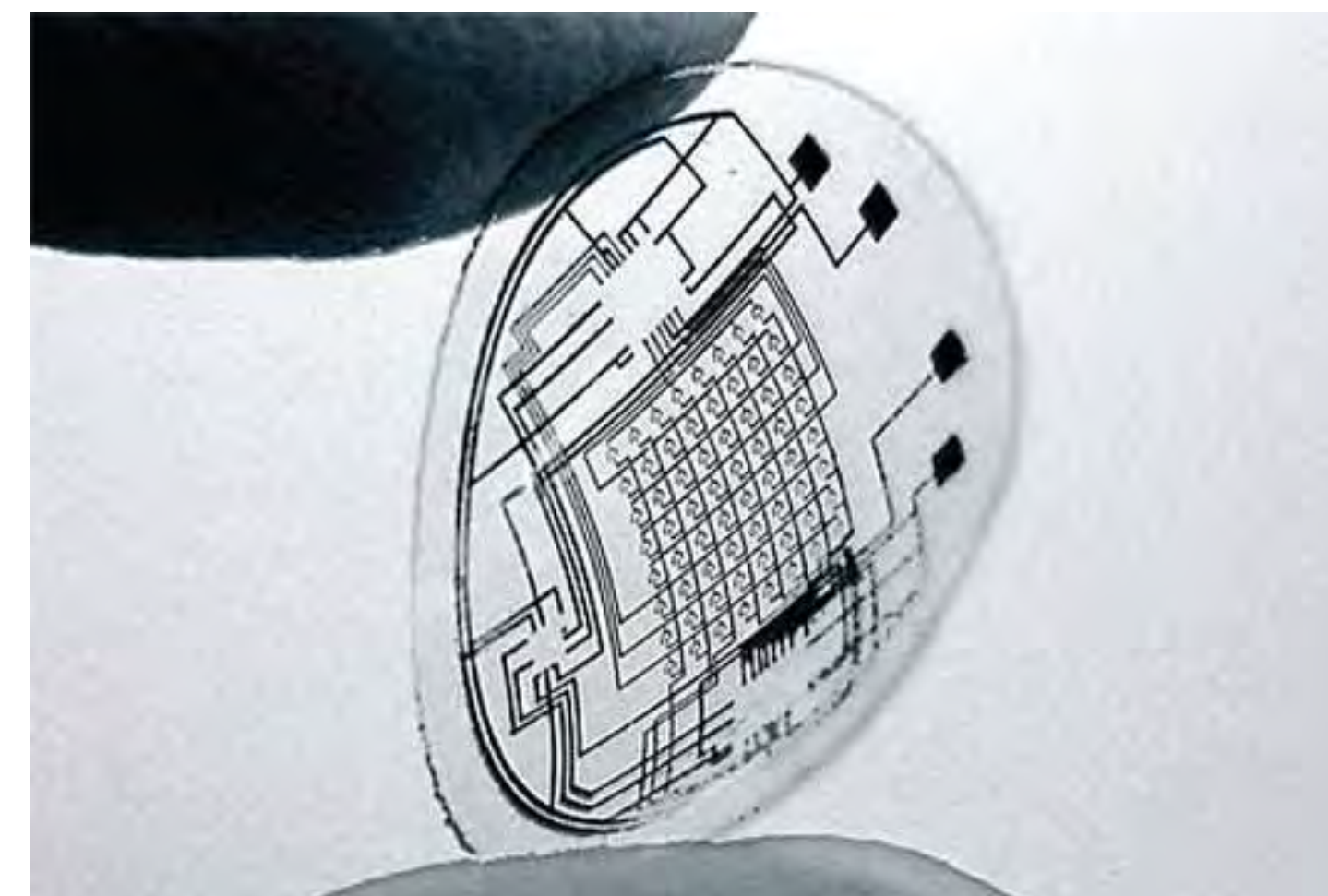


- MagicLeap (2013-)

Contact Lens (10 – 15 + years)

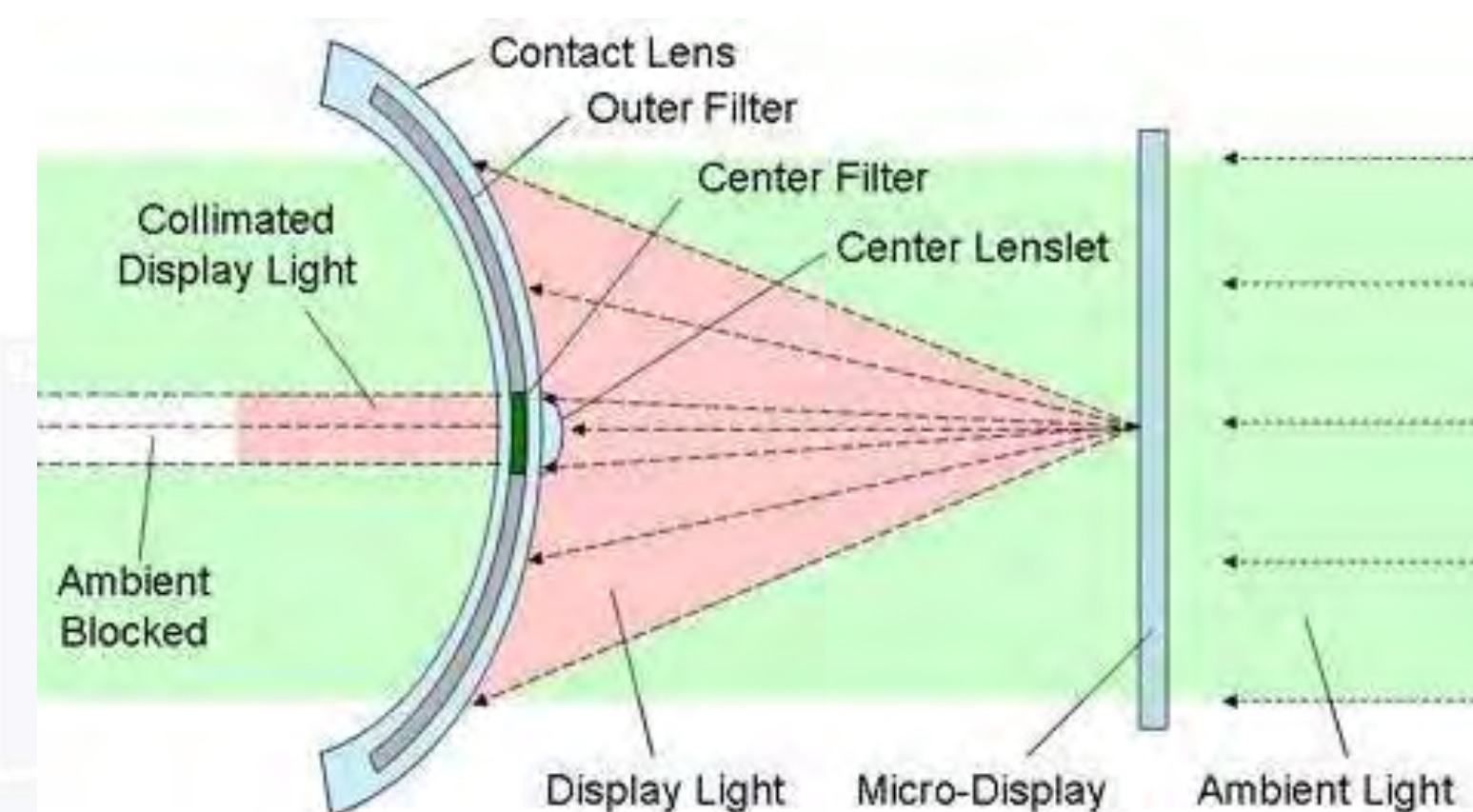
- Contact Lens only

- Unobtrusive
- Significant technical challenges
 - Power, data, resolution
- Babak Parviz (2008)



- Contact Lens + Micro-display

- Wide FOV
- socially acceptable
- Innovega (innovega-inc.com)



<http://spectrum.ieee.org/biomedical/bionics/augmented-reality-in-a-contact-lens/>

Interaction

- Past

- Limited interaction
- Viewpoint manipulation



- Present

- Screen based, simple gesture
- tangible interaction



- Future

- Natural gesture, Multimodal
- Intelligent Interfaces
- Physiological/Sensor based

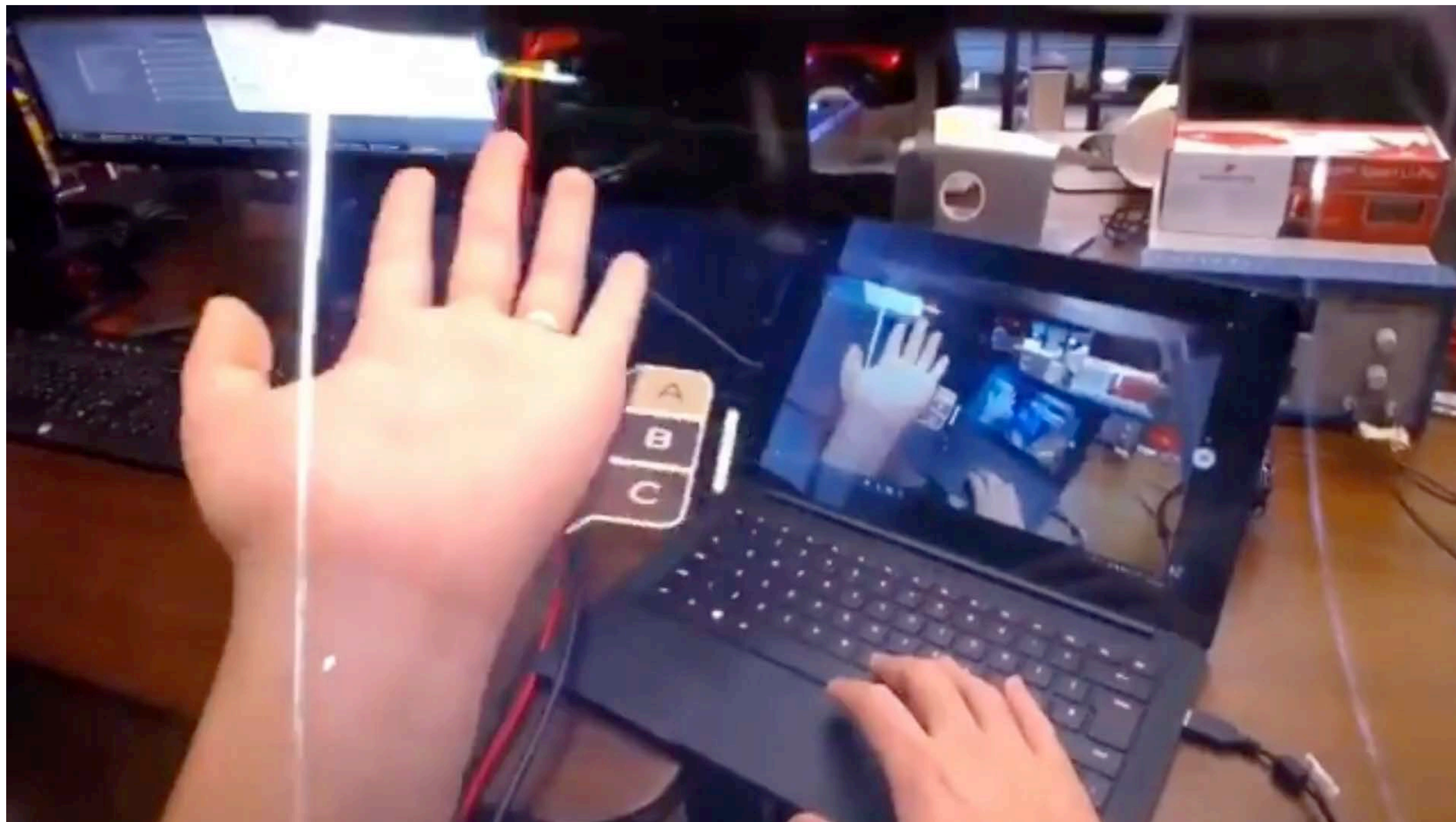


Natural Gesture (2-5 years)

- Freehand gesture input
 - Depth sensors for gesture capture
 - Rich two handed gestures
- E.g. Microsoft Research Hand Tracker
 - 3D hand tracking, 30 fps, single sensor
- Commercial Systems
 - Meta, MS Hololens, Oculus Leap Motion, Intel, etc



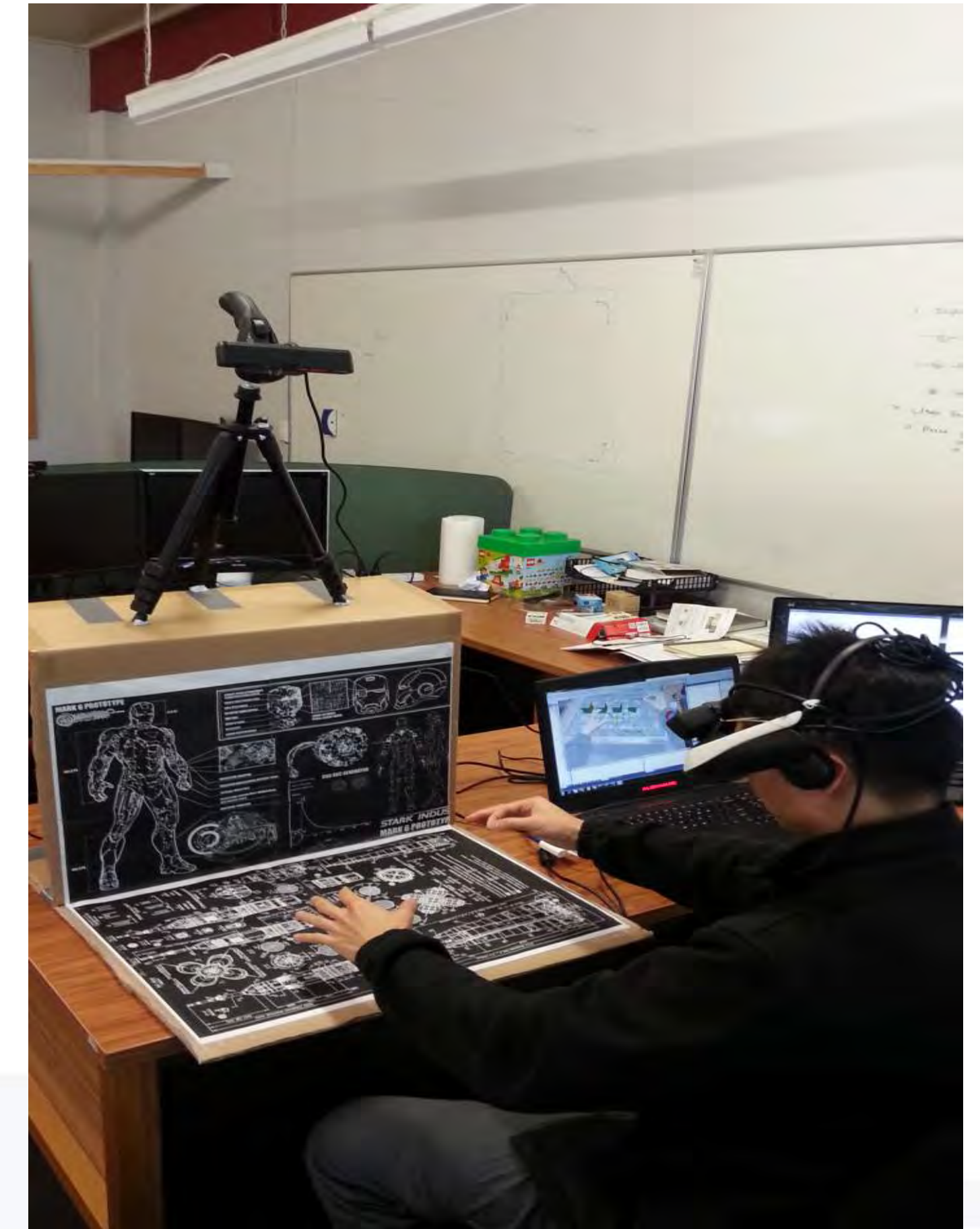
Sharp, F., Keskin, C., Robertson, D., Taylor, J., Shotton, J., Leichter, D. K. C. R. I., ... & Izadi, S. (2015, April). Accurate, Robust, and Flexible Real-time Hand Tracking. In *Proc. CHI* (Vol. 8)



<https://www.youtube.com/watch?v=LblxKvbfEoo>

Multimodal Input (5-10+ years)

- Combine gesture and speech input
 - Gesture good for qualitative input
 - Speech good for quantitative input
 - Support combined commands
 - “Put that there” + pointing
- E.g. HIT Lab NZ multimodal input
 - 3D hand tracking, speech, multimodal fusion



- Complete tasks faster with MM, less errors. (2014). Hands in Space: Gesture Interaction with Augmented-Reality Interfaces. *IEEE computer graphics and applications*, (1), 77-80.

HIT Lab NZ Multimodal Input



Tracking

- Past

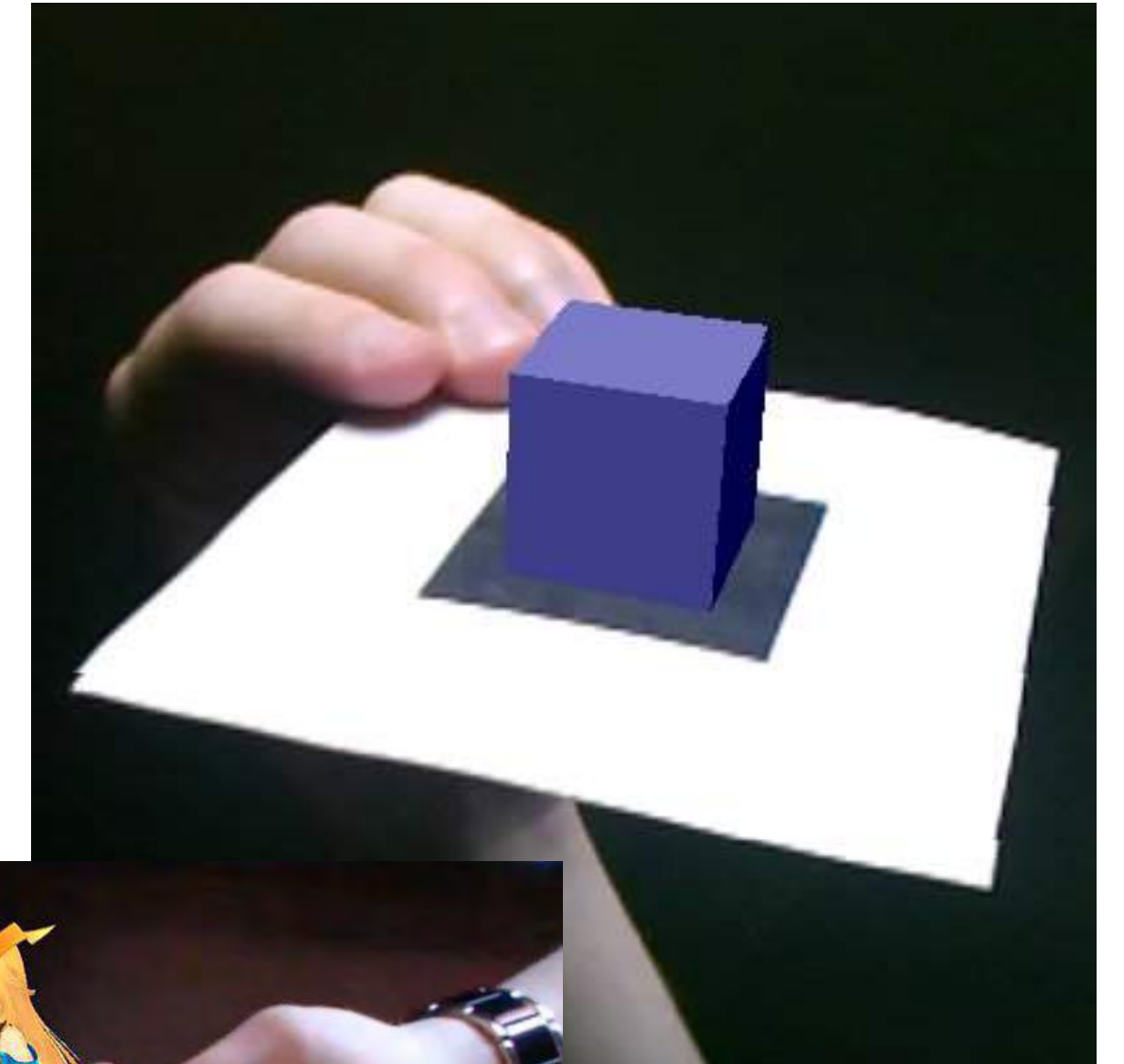
- Location based, marker based,
- magnetic/mechanical

- Present

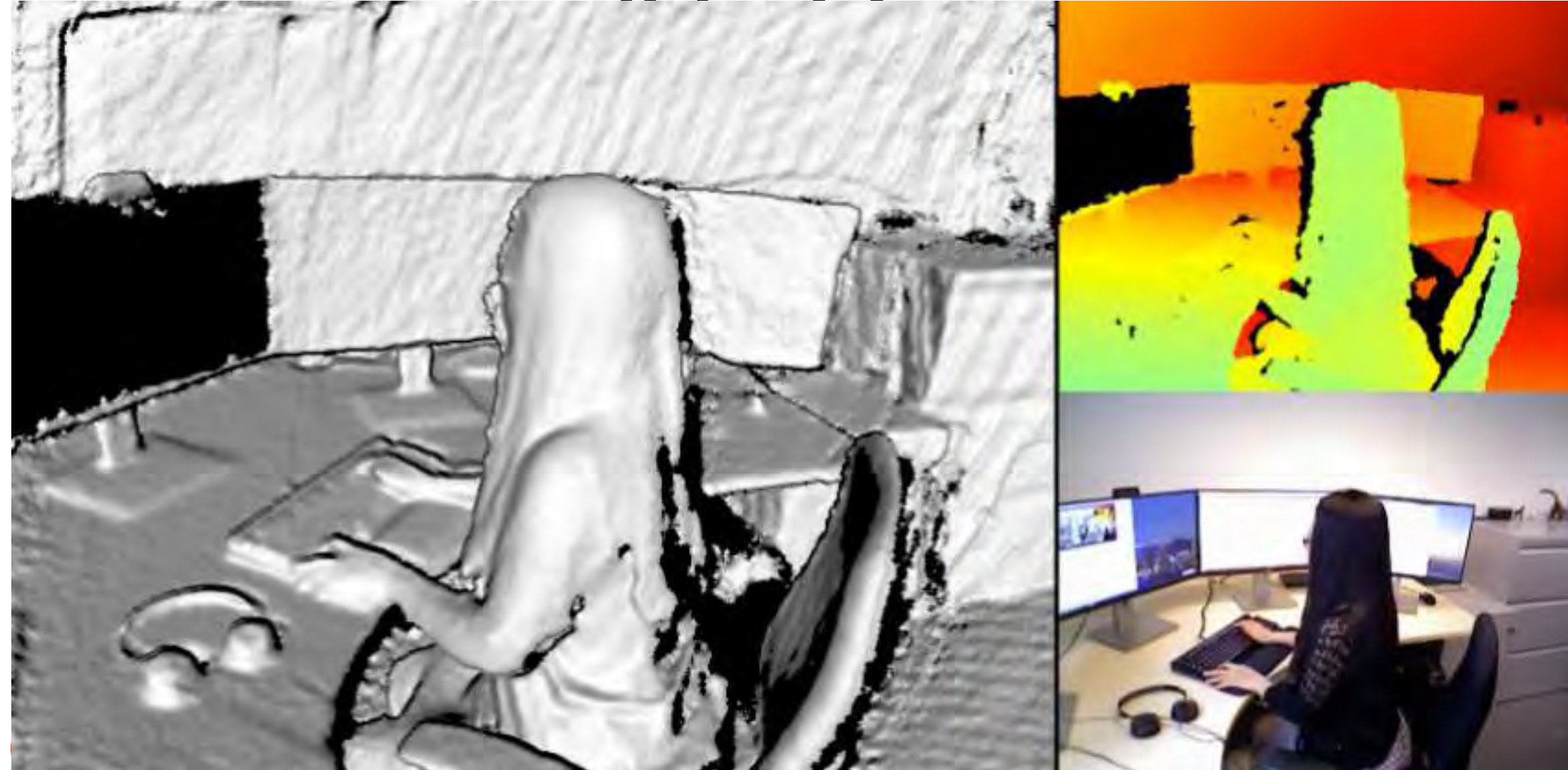
- Image based, hybrid tracking

- Future

- Ubiquitous
- Model based
- Environmental



Environmental Tracking (1-3+ vrs)



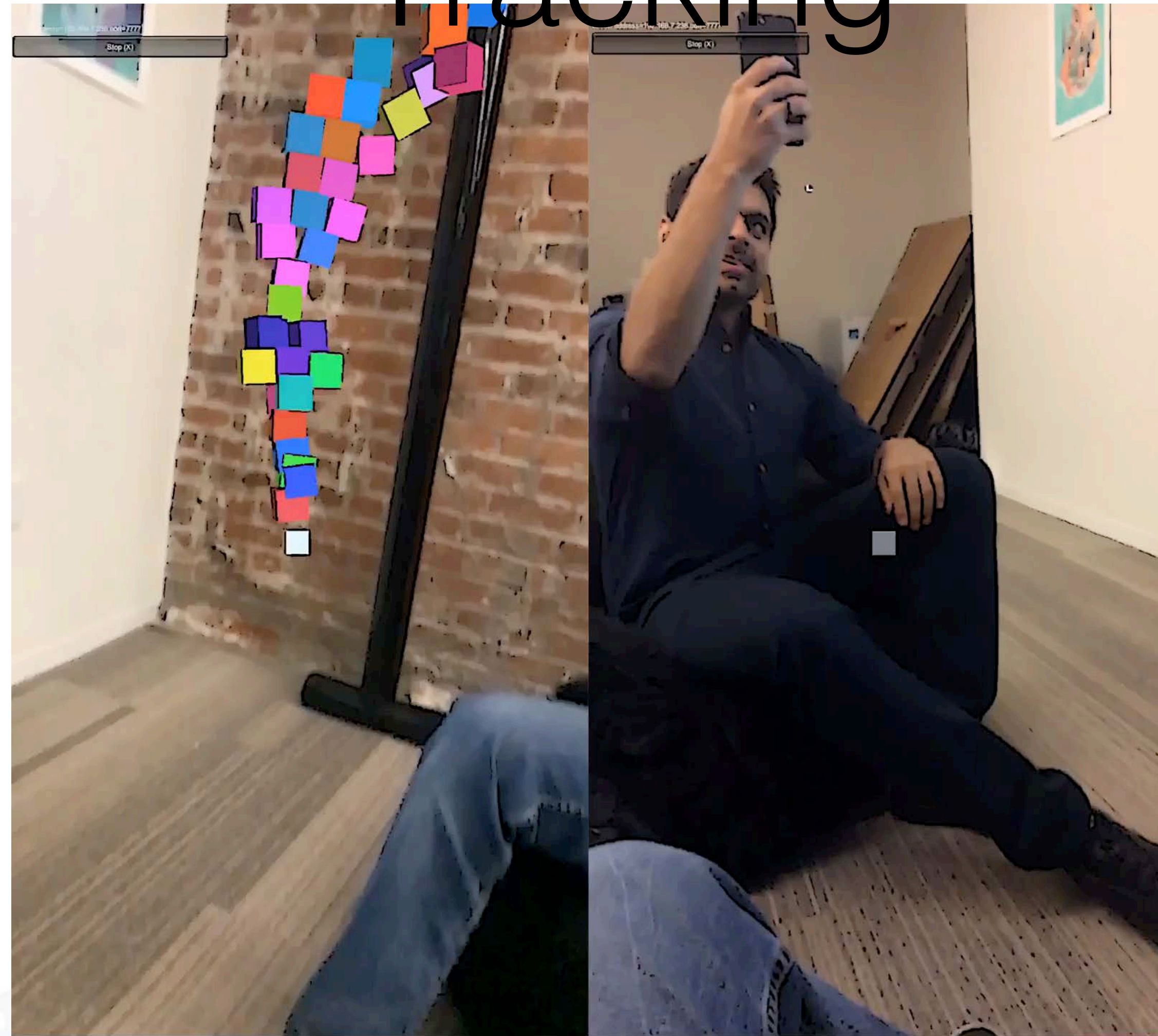
- Environment capture
 - Use depth sensors to capture scene & track from model
- InifinitAM (www.robots.ox.ac.uk/~victor/inifinitam/)
 - Real time scene capture on mobiles, dense or sparse capture

InfiniAM Demo



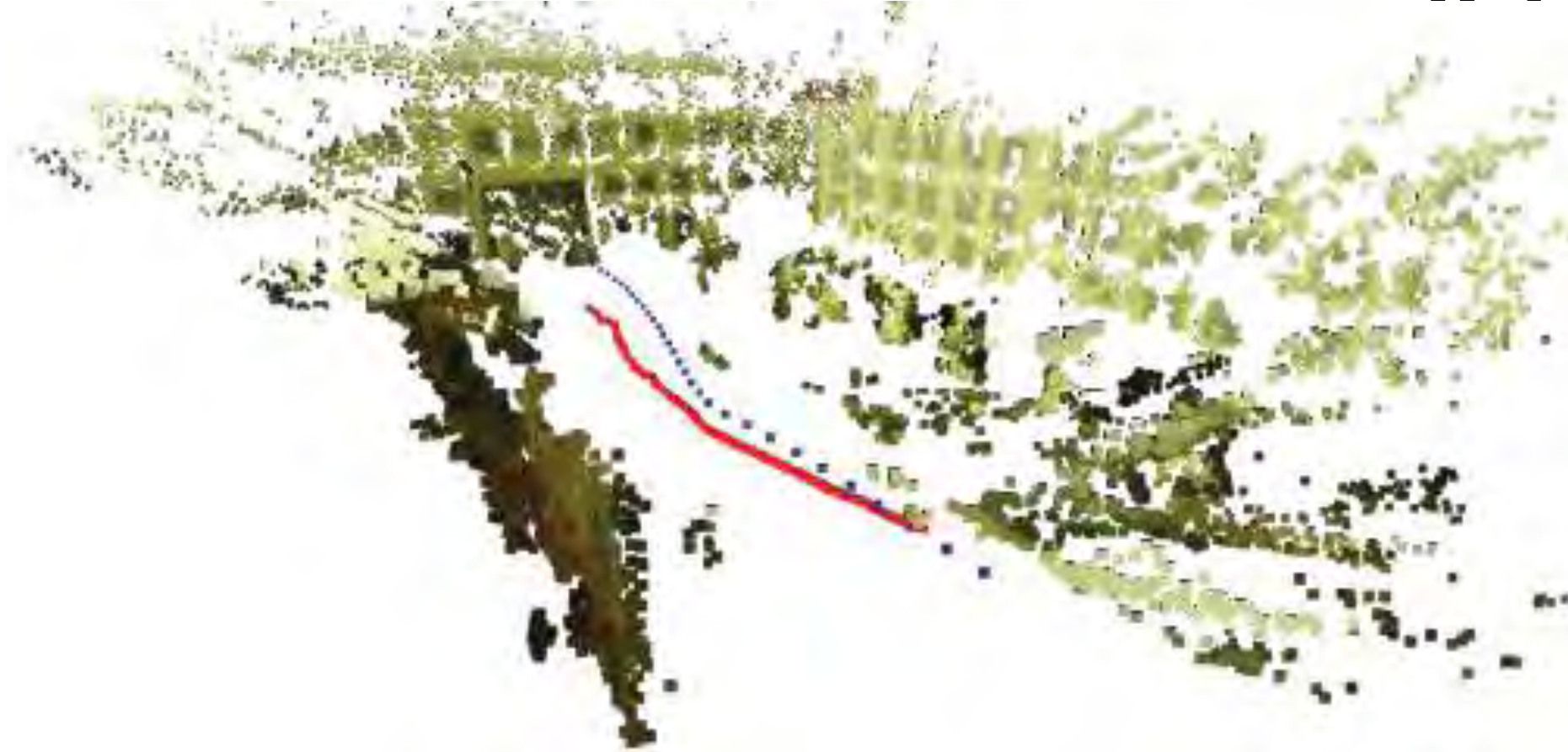
<https://www.youtube.com/watch?v=47zTHHxJjQU>

Ubiquity6 - AR Cloud Tracking



https://www.youtube.com/watch?v=LxQY_7COzQg

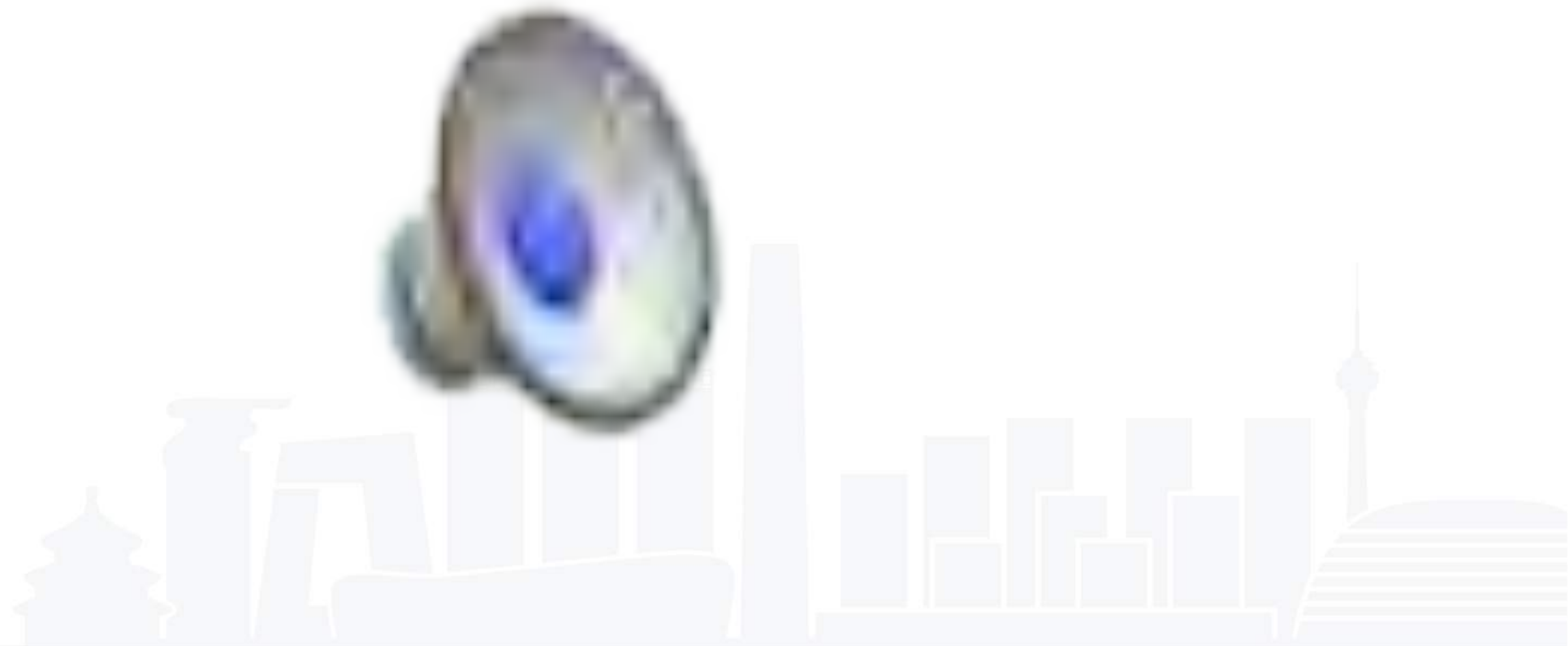
Wide Area Outdoor Tracking (5 + vrs)



- Combine panorama's into point cloud model (omni)
- Initialize camera tracking from point cloud
- Update pose by aligning camera image to point cloud
- Accurate to 25 cm, 0.5 degree over very wide area

Ventura, J., & Hollerer, T. (2012). Wide-area scene mapping for mobile visual tracking. In *Mixed and Augmented Reality (ISMAR), 2012 IEEE International Symposium on* (pp. 3-12). IEEE.

Wide Area Outdoor Tracking

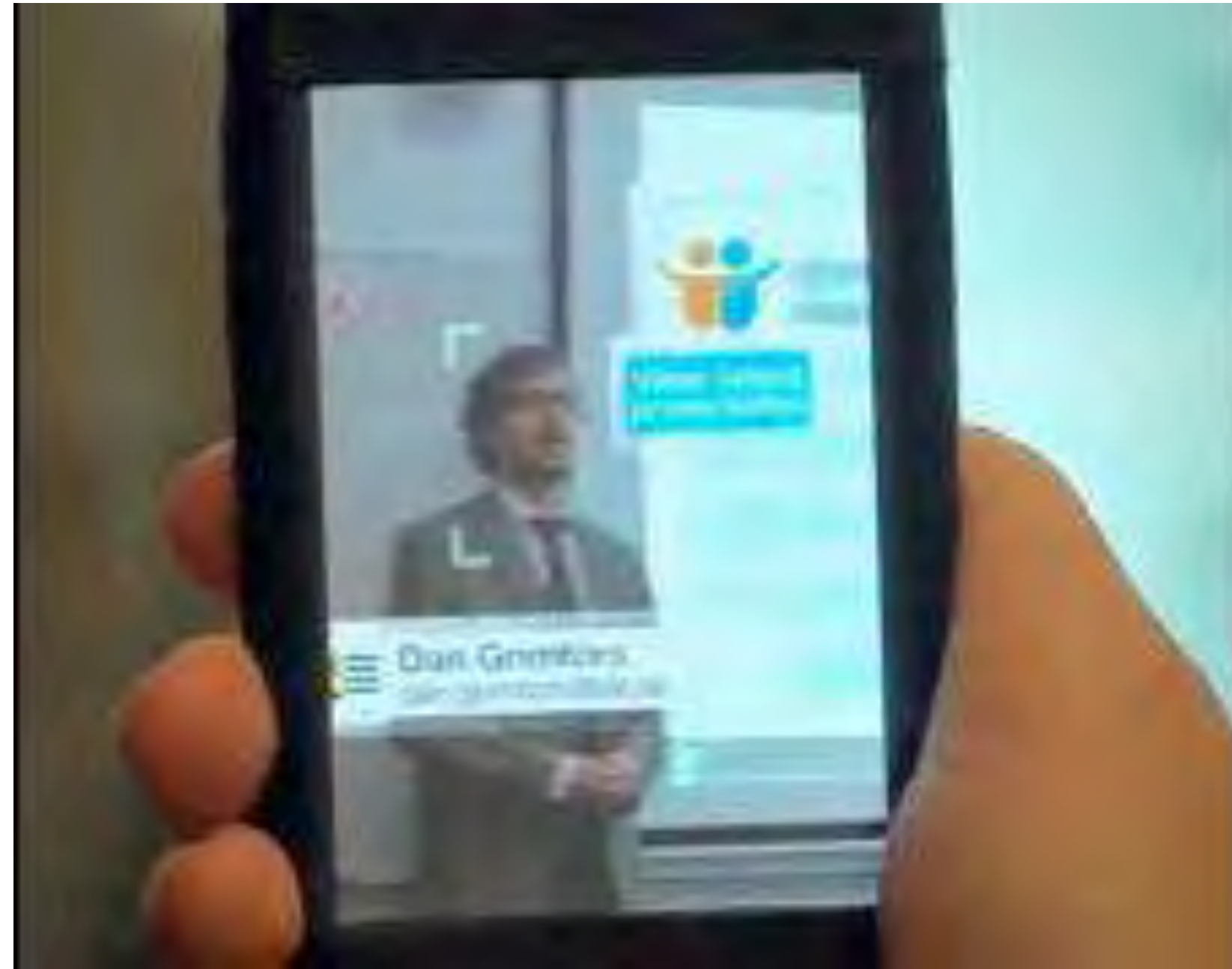


Social Acceptance

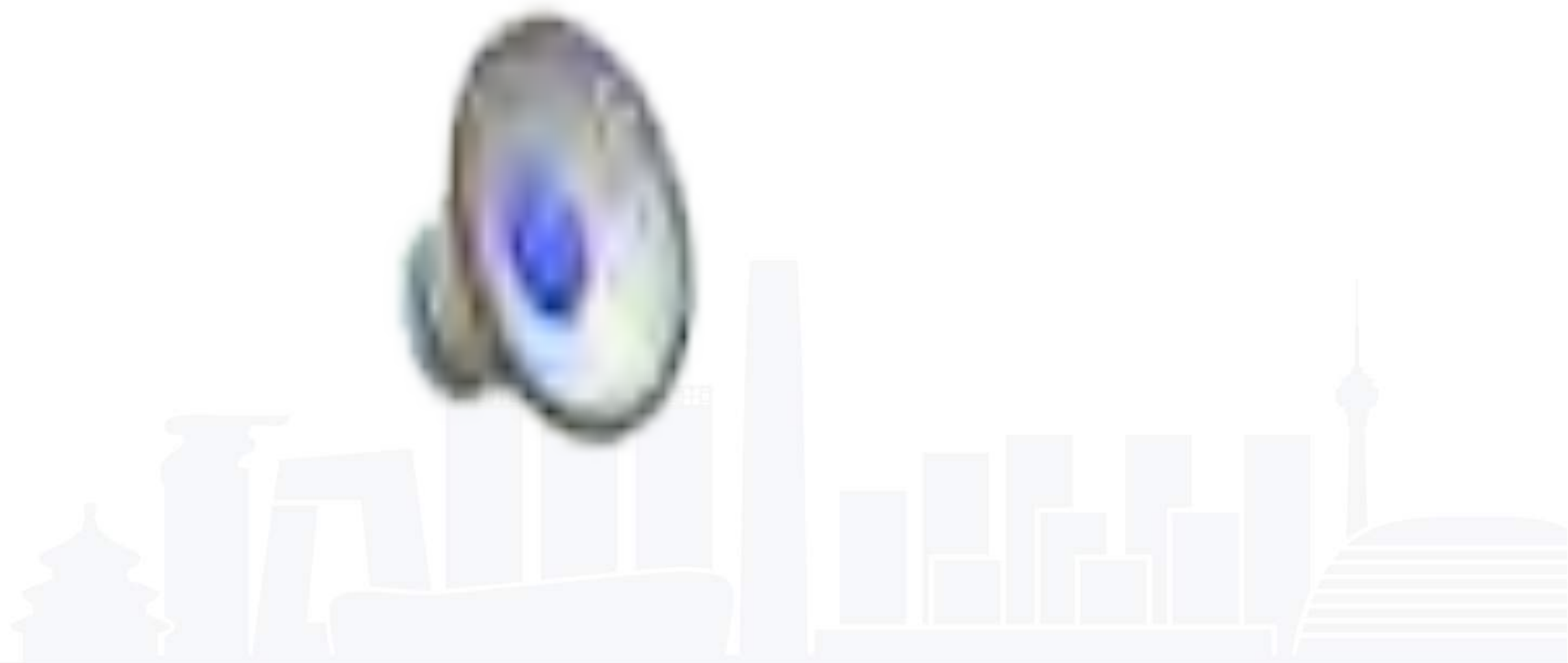


- People don't want to look silly
- Only 12% of 4,600 adults would be willing to wear AR glasses
- 20% of mobile AR browser users experience social issues
- Acceptance more due to Social than Technical issues

Example: TAT Augmented ID



TAT AugmentedID

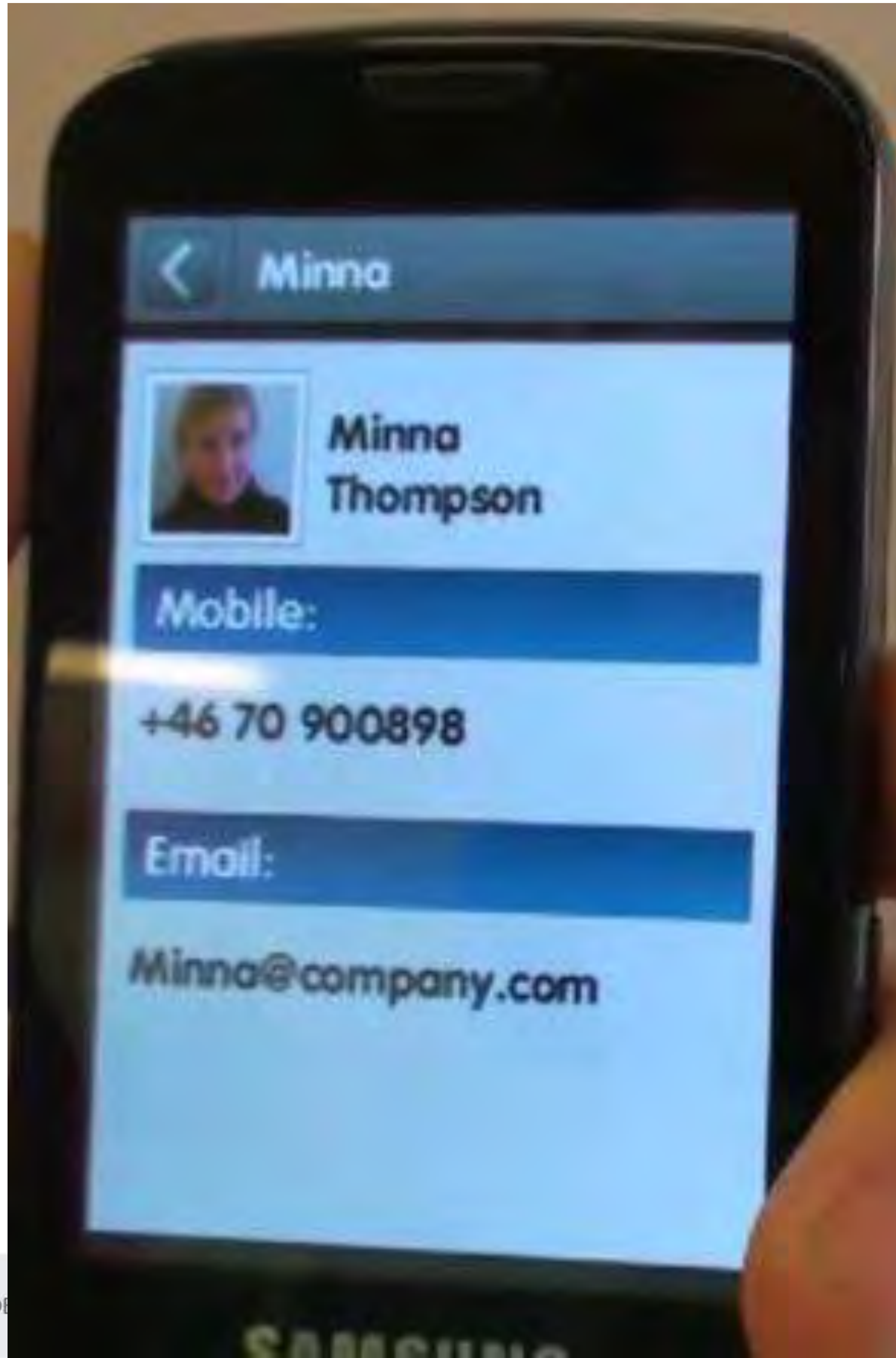


Social Pattern

Like being stopped by the police for ID.

Or security scanned!

“Show me your papers.”



Experience

“Anyone pointing a device in my direction to try to identify me better be prepared for either a **law suit**, or a **punch in the face.**”
Anonymous Comment

