



ThoughtWorks®

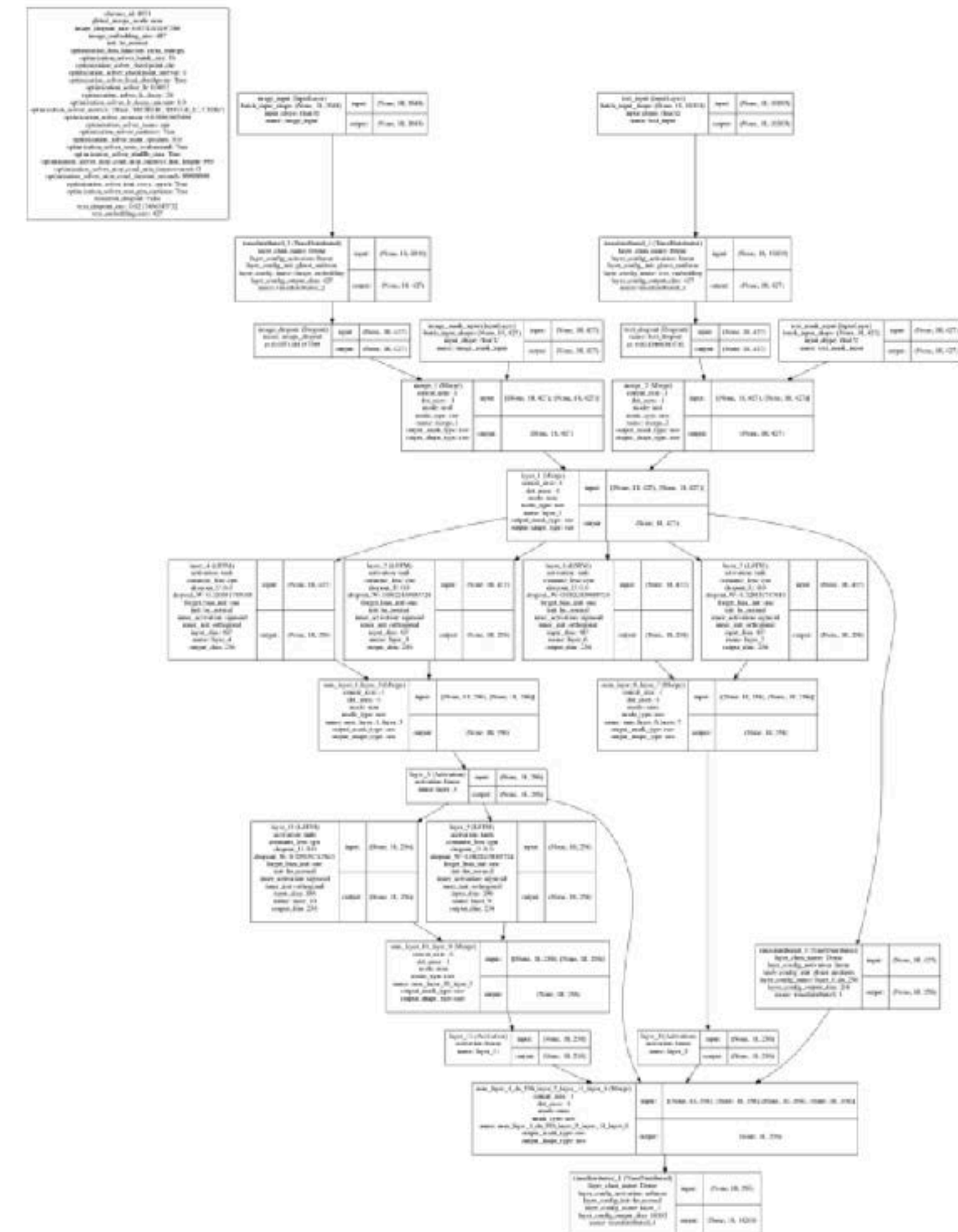
TALK IS CHEAP SHOW ME THE CODE

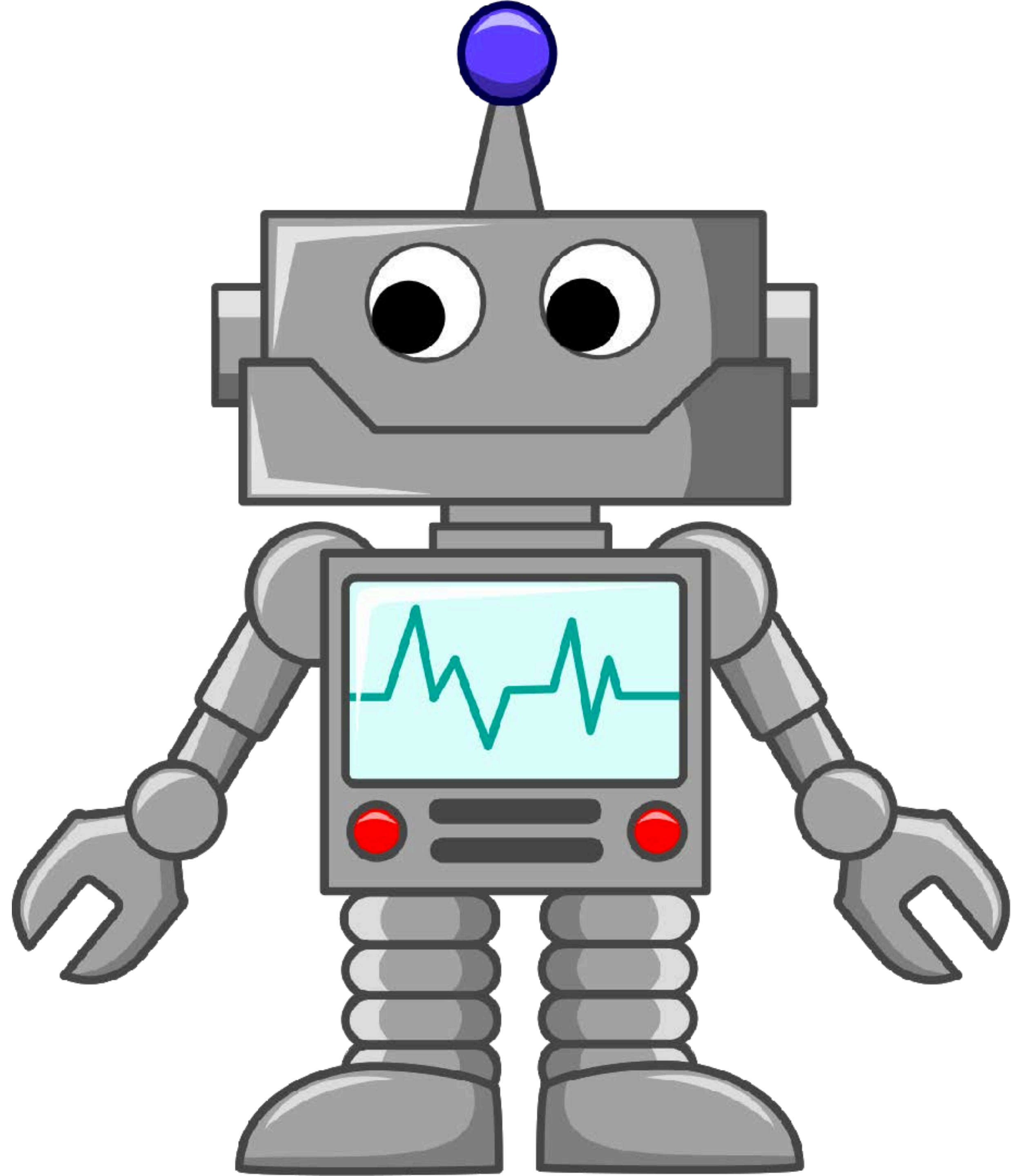
begin with a story

GROWTH OF DATA SCIENCE

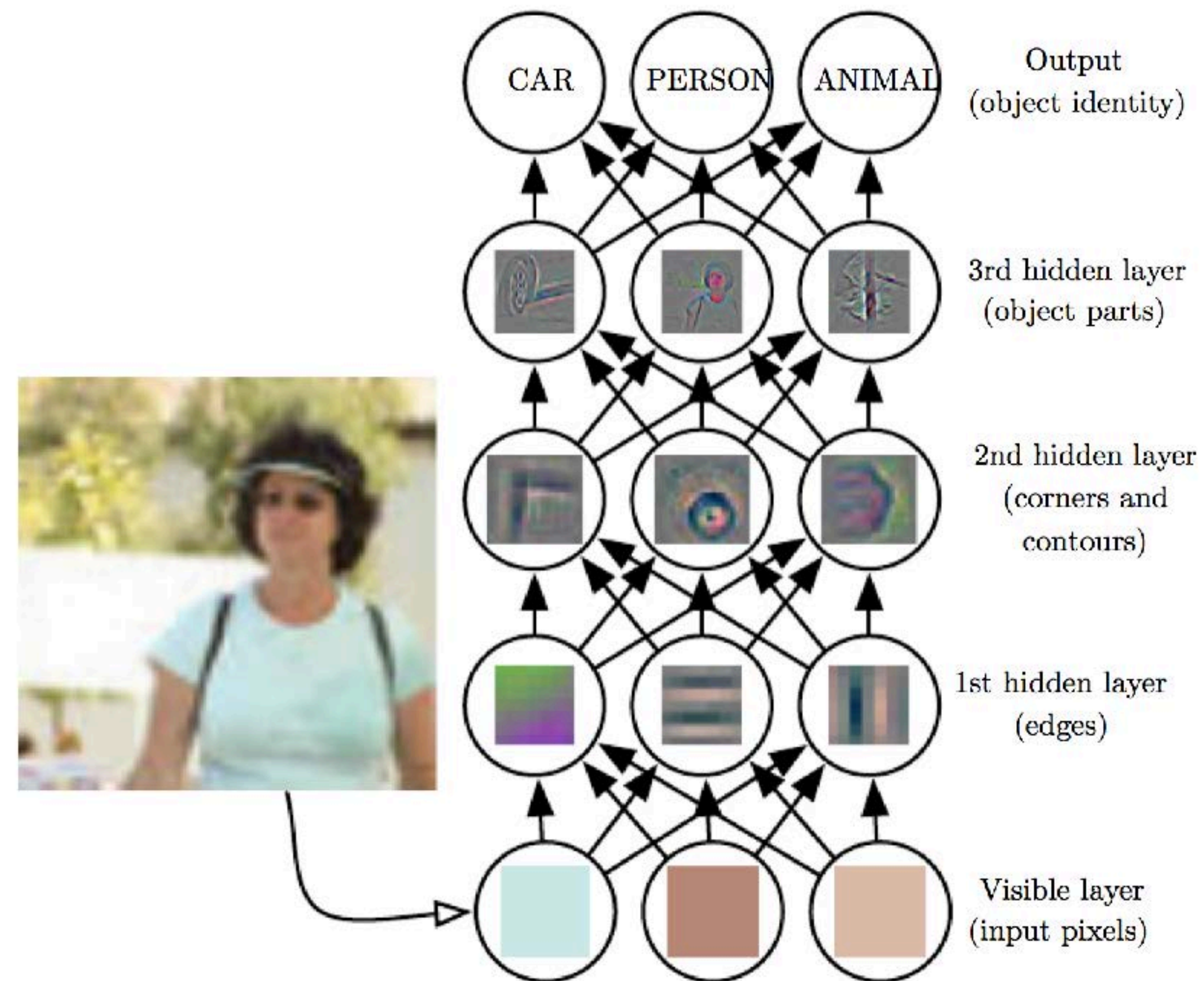
Node Hyperparameter	Range
Number of Filters	[32, 256]
Dropout Rate	[0, 0.7]
Initial Weight Scaling	[0, 2.0]
Kernel Size	{1, 3}
Max Pooling	{True, False}
Global Hyperparameter	Range
Learning Rate	[0.0001, 0.1]
Momentum	[0.68, 0.99]
Hue Shift	[0, 45]
Saturation/Value Shift	[0, 0.5]
Saturation/Value Scale	[0, 0.5]
Cropped Image Size	[26, 32]
Spatial Scaling	[0, 0.3]
Random Horizontal Flips	{True, False}
Variance Normalization	{True, False}
Nesterov Accelerated Gradient	{True, False}

Table 1: Node and global hyperparameters evolved in the CIFAR-10 domain.





DEEP LEARNING



Deep Learning

Ian Goodfellow Yoshua
Bengio Aaron Courville



ThoughtWorks®

NEURO NETWORK IS FUNCTIONAL PROGRAMMING

deeplearning.scala



DeepLearning.scala

Differentiable
Programming

Functional
Programming

Dynamic Neural
Networks

Plugins

IQ TEST ROBOT

What is the next number in the sequence?

3,4,5,?

13,19,25,?

THE SIGNATURE OF IQ TEST ROBOT

```
def guessNextNumber(question: Seq[Double]): DoubleLayer = ???
```

```
println(guessNextNumber(Seq(3, 4, 5)).predict.blockingAwait)
```

```
println(guessNextNumber(Seq(13, 19, 25)).predict.blockingAwait)
```

TRAINING THE IQ TEST ROBOT

```
def lossFunction(robotAnswer: DoubleLayer, expectedAnswer: Double): DoubleLayer = ???

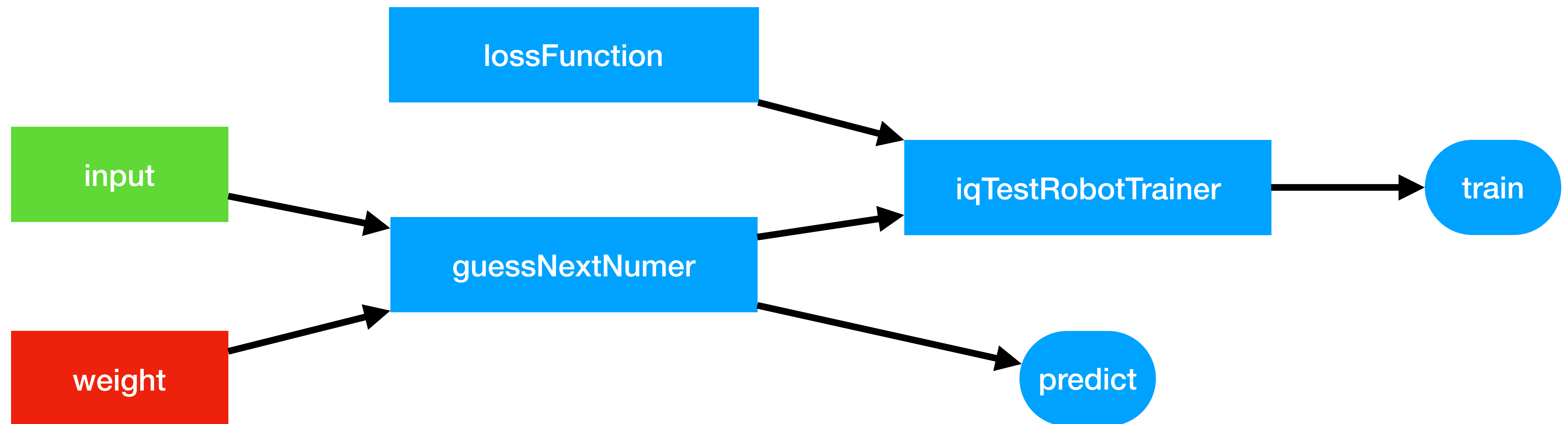
def iqTestRobotTrainer(question: Seq[Double], expectedAnswer: Double): DoubleLayer = {
  val robotAnswer = guessNextNumber(question)
  lossFunction(robotAnswer, expectedAnswer)
}

iqTestRobotTrainer(Seq(3, 4, 5), 6).train.blockingAwait
iqTestRobotTrainer(Seq(13, 19, 25), 31).train.blockingAwait
```

TRAINING IN TENSORFLOW

```
pred_x = model(X, w_h, w_o)
loss = tf.reduce_mean(tf.nn.lossfunction(pred_x, Y))
train_op = tf.train.GradientDescentOptimizer(0.05).minimize(loss)
```

FUNCTIONS ARE COMPOSED



TRAINING THE IQ TEST ROBOT

```
def lossFunction(robotAnswer: DoubleLayer, expectedAnswer: Double): DoubleLayer = ???

def iqTestRobotTrainer(question: Seq[Double], expectedAnswer: Double): DoubleLayer = {
  val robotAnswer = guessNextNumber(question)
  lossFunction(robotAnswer, expectedAnswer)
}

iqTestRobotTrainer(Seq(3, 4, 5), 6).train.blockingAwait
iqTestRobotTrainer(Seq(13, 19, 25), 31).train.blockingAwait
```

THE STRUCTURE OF THE IQ TEST ROBOT

```
// A vector of weights that are lazily initialized
val weights: Stream[DoubleWeight] =
Stream.continually(DoubleWeight(math.random))

// The predictor implemented with map/reduce
def guessNextNumber(question: Seq[Double]): DoubleLayer = {
  (question zip weights).map {
    case (element, weight) => element * weight
  }.reduce(_ + _)
}

// Square loss function
def lossFunction(robotAnswer: DoubleLayer, expectedAnswer:
Double): DoubleLayer = {
  val difference: DoubleLayer = robotAnswer - expectedAnswer
  difference * difference
}
```

SOLUTION IN TENSORFLOW

```
def model(X, w_h, w_o):  
    h = tf.nn.relu(tf.matmul(X, w_h))  
    return tf.matmul(h, w_o)
```

THE STRUCTURE OF THE IQ TEST ROBOT

```
// A vector of weights that are lazily initialized
val weights: Stream[DoubleWeight] =
Stream.continually(DoubleWeight(math.random))

// The predictor implemented with map/reduce
def guessNextNumber(question: Seq[Double]): DoubleLayer = {
  (question zip weights).map {
    case (element, weight) => element * weight
  }.reduce(_ + _)
}

// Square loss function
def lossFunction(robotAnswer: DoubleLayer, expectedAnswer:
Double): DoubleLayer = {
  val difference: DoubleLayer = robotAnswer - expectedAnswer
  difference * difference
}
```

META-PROGRAMMING

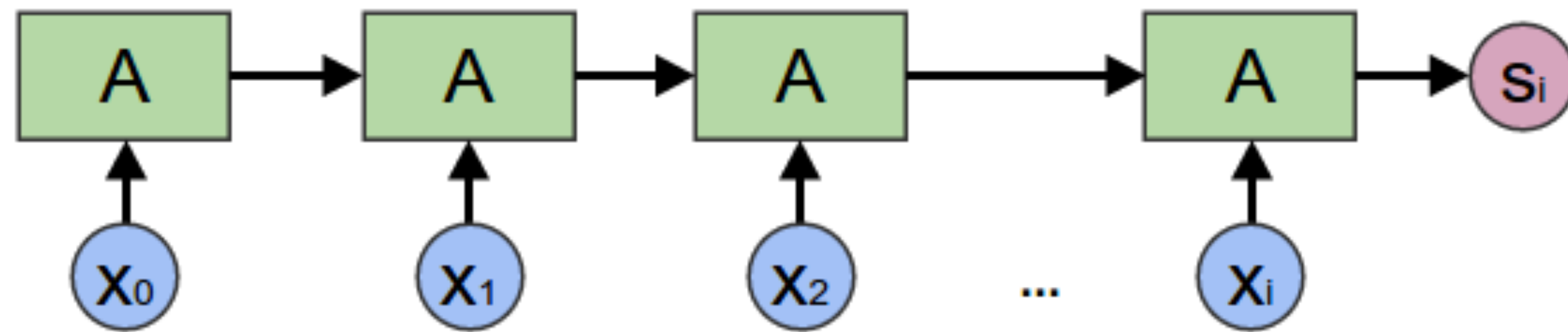


<https://prateekvjoshi.files.wordpress.com/2014/04/1-main.png>

CORRESPONDING BETWEEN NEURAL NETWORK AND FUNCTIONAL PROGRAMMING

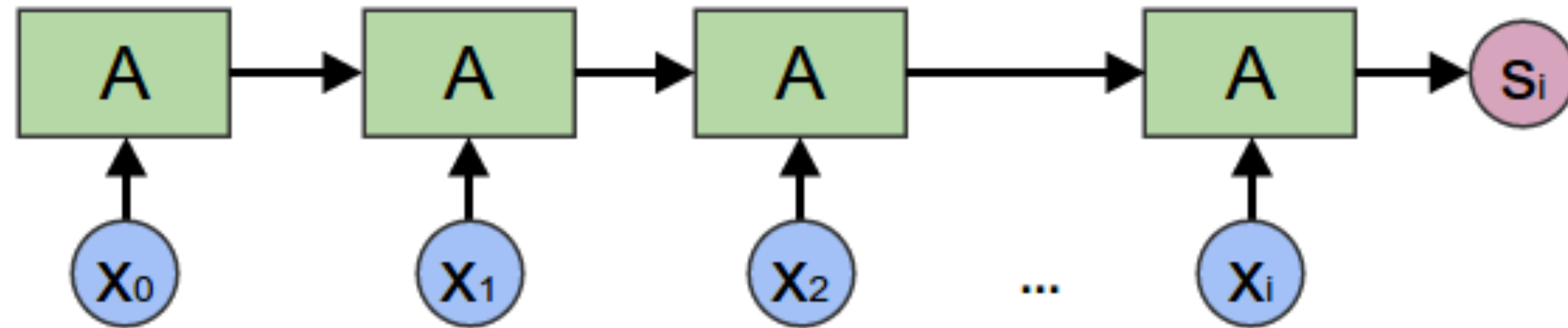
yes it is

ENCODING RECURRENT NEURAL NETWORKS



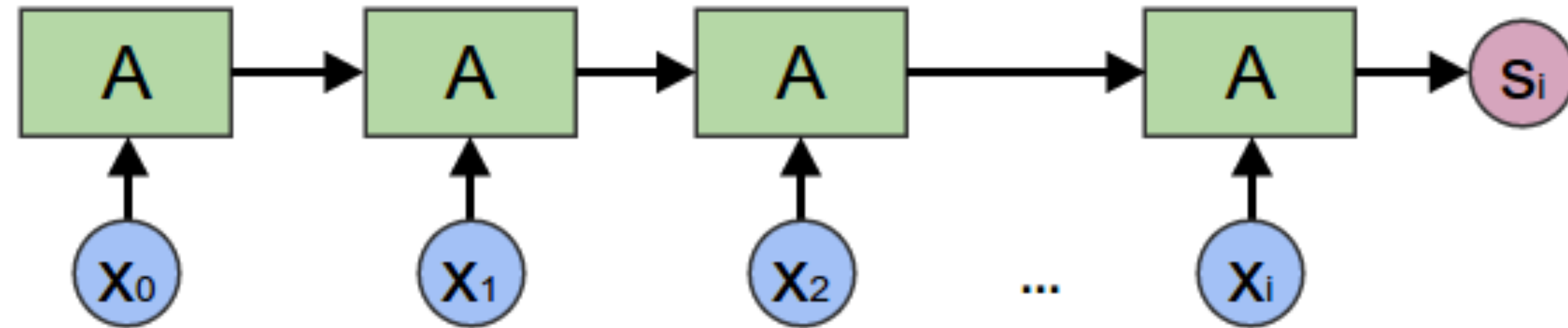
<https://colah.github.io/posts/2015-09-NN-Types-FP/>

ENCODING RECURRENT NEURAL NETWORKS



```
package scala.collection
trait Seq[A] {
  def foldLeft[B](z: B)(step: (B, A) => B): B
}
```

ENCODING RECURRENT NEURAL NETWORKS

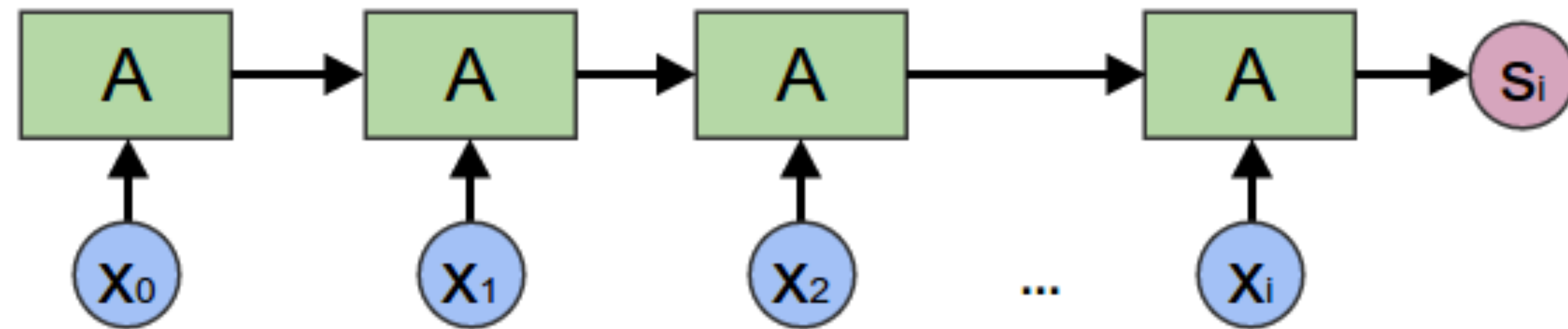


```
type Input = Seq[DoubleLayer]
type State = Seq[DoubleLayer]
```

```
def step(hiddenState: State, xi: Input): State = ???
```

```
def encodingRNN(x: Seq[Input]): State = {
  val initialState: State = Seq.empty[DoubleLayer]
  x.foldLeft(initialState)(step)
}
```

ENCODING RECURRENT NEURAL NETWORKS

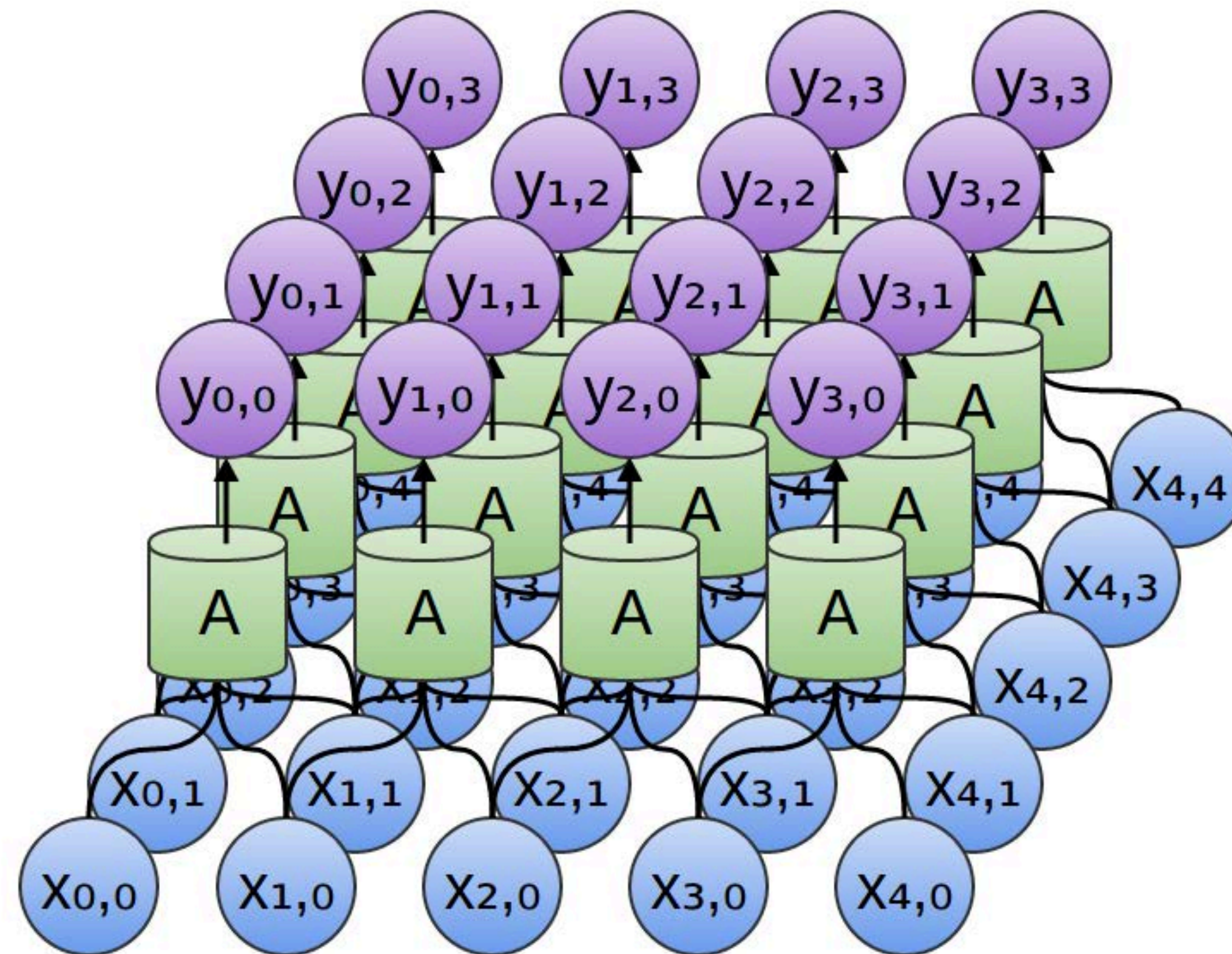


```
val NumberOfOutputFeatures = 10
```

```
val weight: Seq[Seq[DoubleWeight]] = Seq.fill(NumberOfOutputFeatures)(  
    Stream.continually(DoubleWeight(math.random))  
)
```

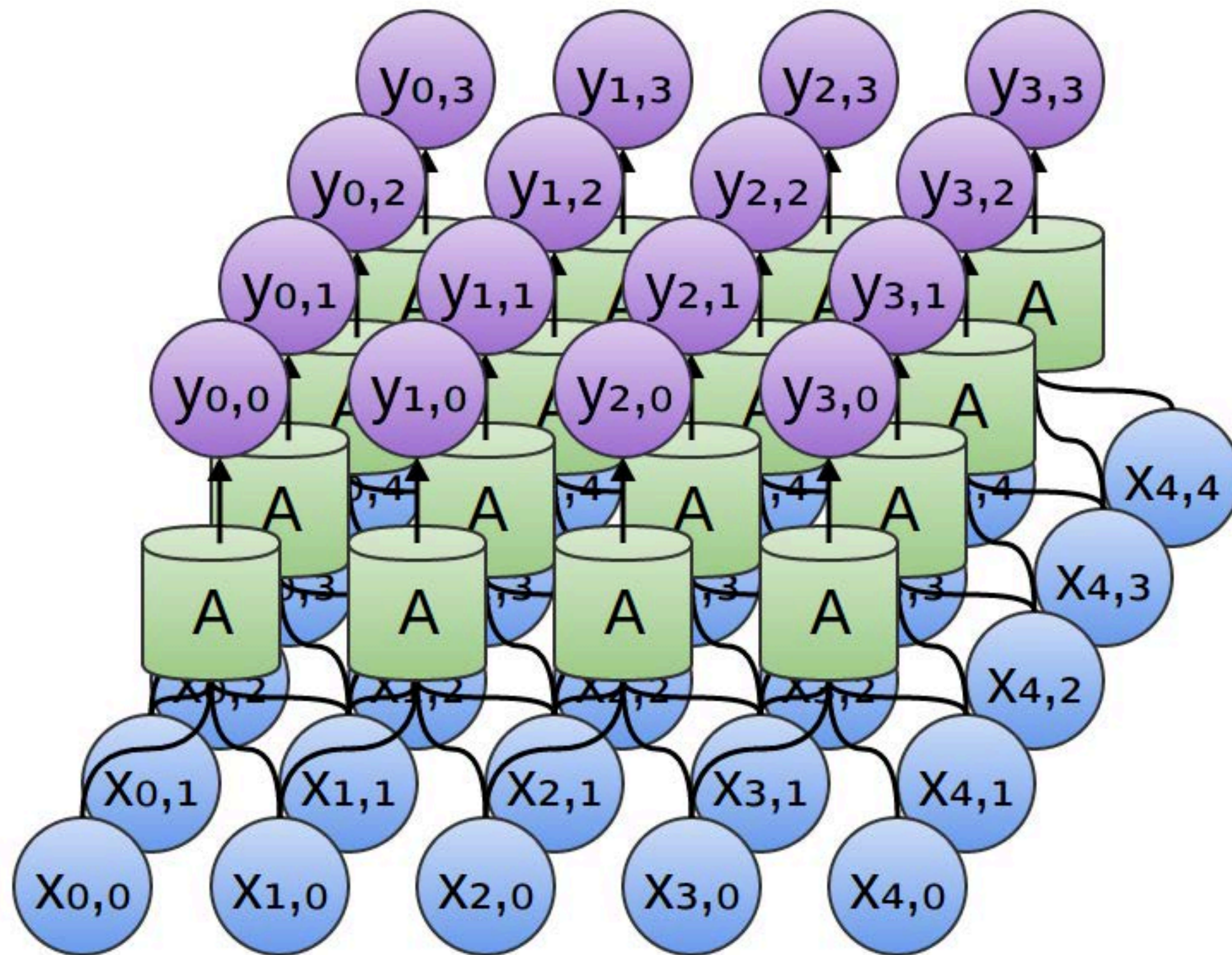
```
def step(hiddenState: State, xi: Input): State = {  
    tanh(matrixMultiply(hiddenState ++ xi, weight))  
}
```

TWO DIMENSIONAL CONVOLUTIONAL NETWORK



<https://colah.github.io/posts/2015-09-NN-Types-FP/>

TWO DIMENSIONAL CONVOLUTIONAL NETWORK



```
type Input = Seq[DoubleLayer]
type Output = Seq[DoubleLayer]

def kernel2x2(xi: Input, xj: Input, xk: Input, xl:
Input): Output

def cnn2d(x: List[List[Input]]): List[Output]) = {
  val x00 = x
  val x01 = x.map(_.tail)
  val x10 = x.tail
  val x11 = x.tail.map(_.tail)
  (x zip x01 zip x10 zip x11).map {
    case (((xi, xj), xk), xl) => kernel2x2(xi, xj, xk,
xl)
  }
}
```

NEURO NETWORK IS FUNCTIONAL PROGRAMMING

Deep Learning Name	Functional Name
Learned Vector	Holes in metaprogramming
Encoding RNN	Fold
Generating RNN	Unfold
General RNN	Accumulating Map
Bidirectional RNN	Zipper Left/Right Accumulating Maps
Conv Layer	“Window Map”
TreeNet	scanr

ThoughtWorks®

MONADIC DEEP LEARNING

dynamically

MIXTURE OF EXPERTS

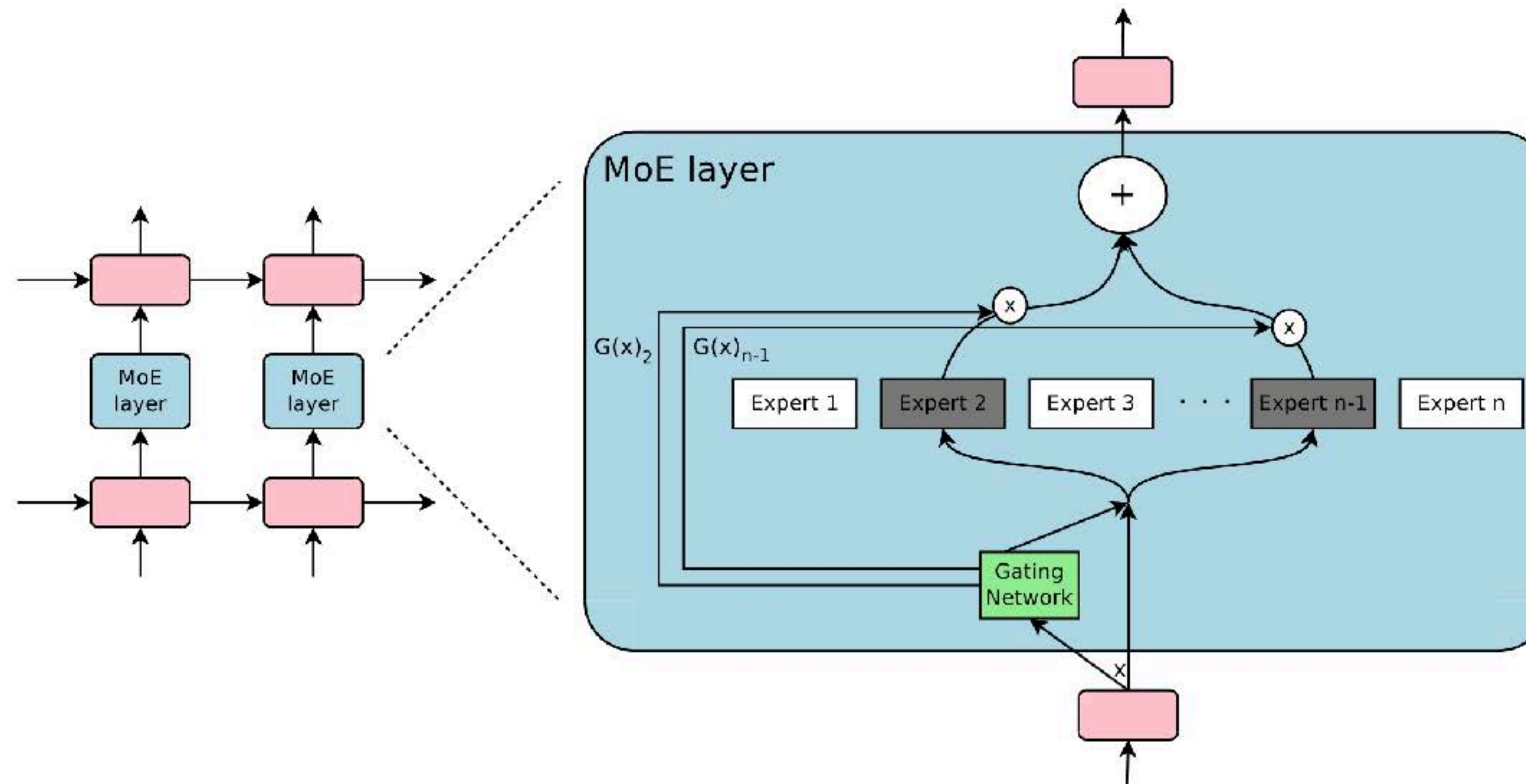


Figure 1: A Mixture of Experts (MoE) layer embedded within a recurrent language model. In this case, the sparse gating function selects two experts to perform computations. Their outputs are modulated by the outputs of the gating network.

NAIVE GATED NET

```
type Input = INDArrayLayer
type Output = INDArrayLayer
type Condition = (DoubleLayer, DoubleLayer)

def leftSubnet(input: Input): Output = ???
def rightSubnet(input: Input): Output = ???
def gate(input: Input): Condition = ???

def naiveGatedNet(input: Input): Output = {
  val condition = gate(input)
  if (condition._1.predict.blockingAwait > condition._2.predict.blockingAwait) {
    condition._1 * leftSubnet(input)
  } else {
    condition._2 * rightSubnet(input)
  }
}
```

NAIVE GATED NET

NAIVE GATED NET

`gate(input)._1`

execution of computation #1

NAIVE GATED NET

`gate(input)._1`

execution of computation #1

`gate(input)._2`

execution of computation #2

NAIVE GATED NET

gate(input)._1

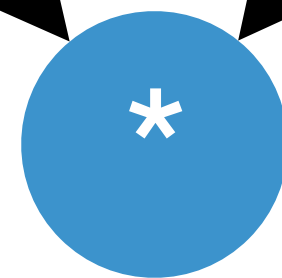
execution of computation #1

gate(input)._2

execution of computation #2

gate(input)._1

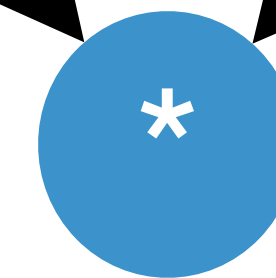
leftSubnet



or

gate(input)._2

rightSubnet



execution of computation #3

MONAD



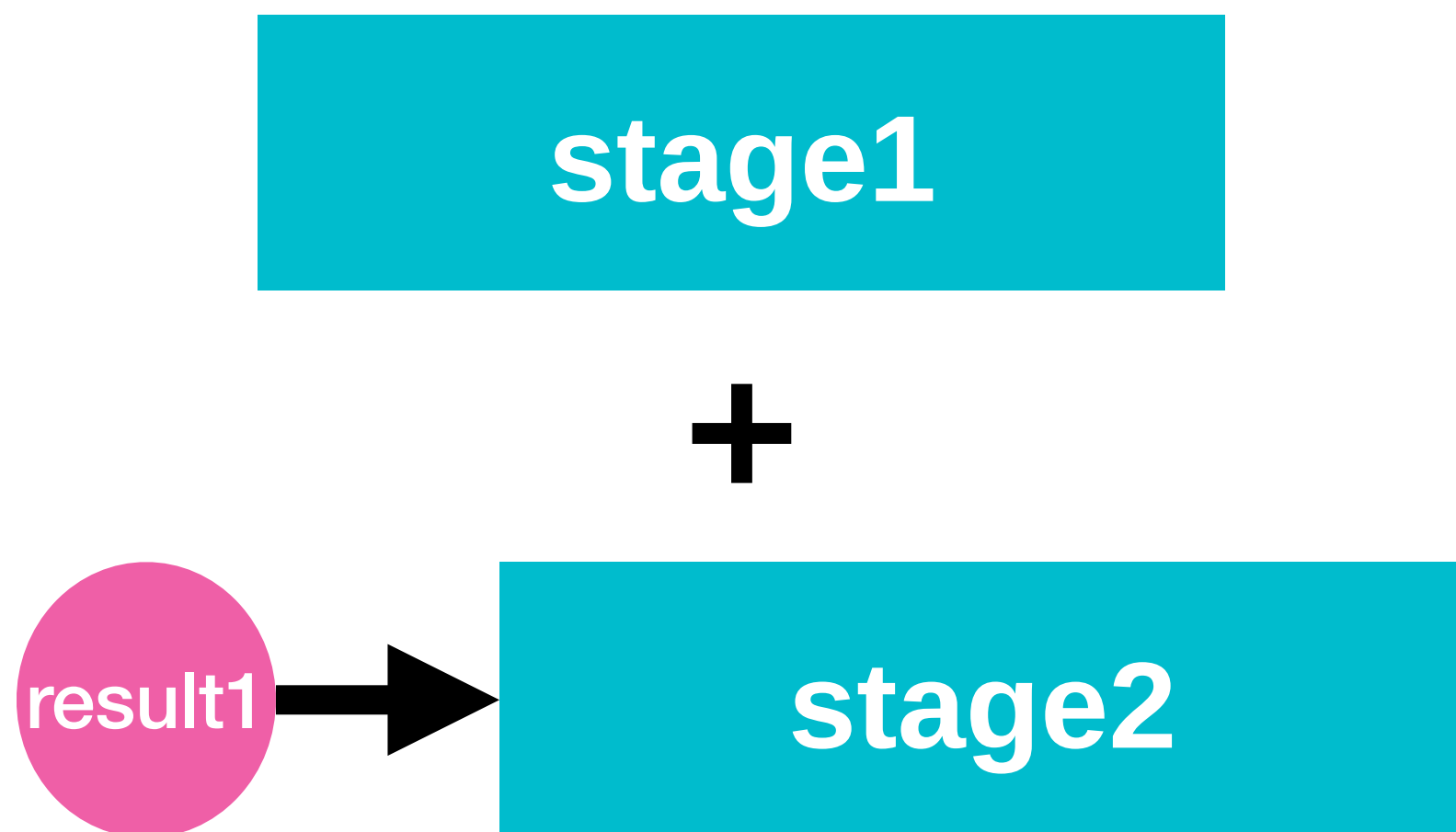
```
class Do[A] {  
  def flatMap[B](f: A => Do[B]) : Do[B]  
}
```

THE USAGE OF FLATMAP

```
val stage1: Do[Stage1Result] = ???  
def stage2(result1: Stage1Result): Do[Stage2Result] = ???  
  
val flatMapped: Do[Stage2Result] = stage1.flatMap(stage2)
```

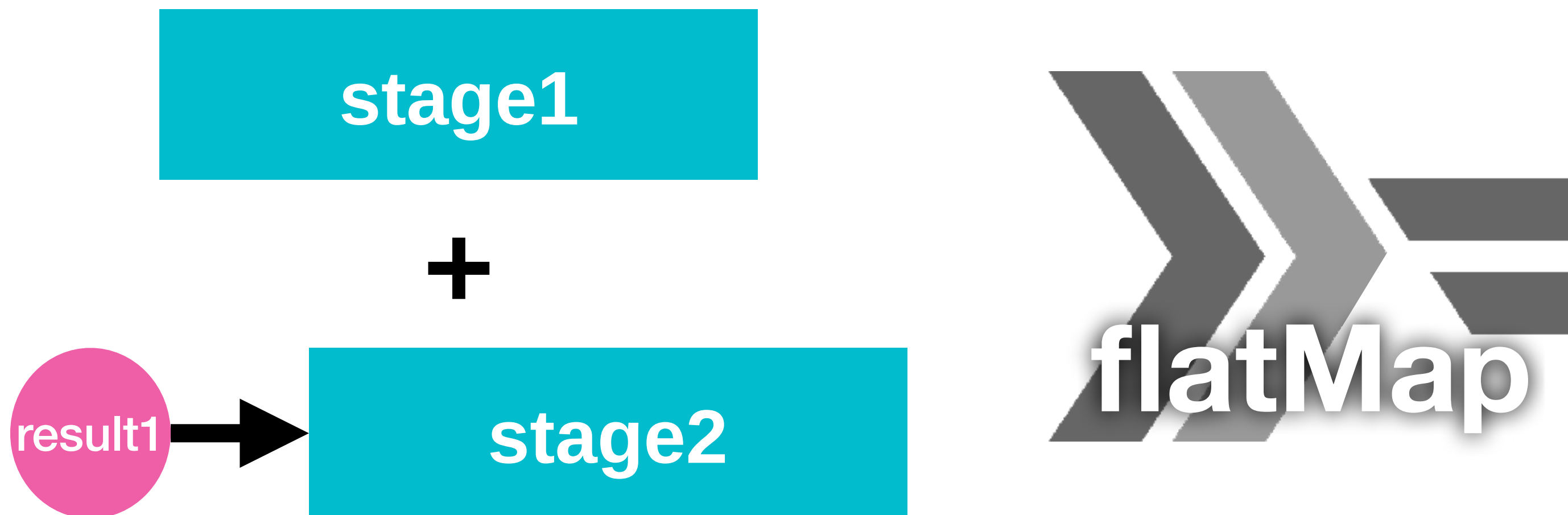
THE USAGE OF FLATMAP

```
val stage1: Do[Stage1Result] = ???  
def stage2(result1: Stage1Result): Do[Stage2Result] = ???  
  
val flatMapped: Do[Stage2Result] = stage1.flatMap(stage2)
```



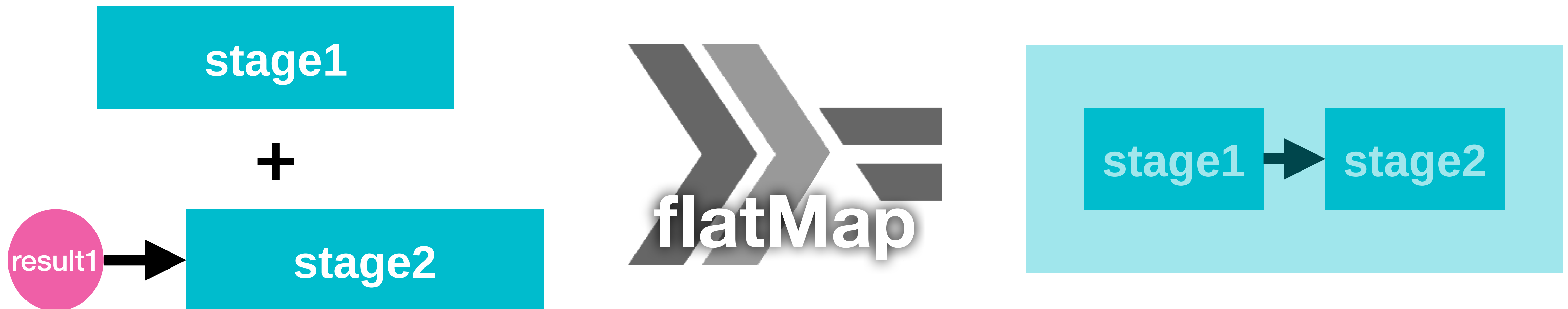
THE USAGE OF FLATMAP

```
val stage1: Do[Stage1Result] = ???  
def stage2(result1: Stage1Result): Do[Stage2Result] = ???  
  
val flatMapped: Do[Stage2Result] = stage1.flatMap(stage2)
```



THE USAGE OF FLATMAP

```
val stage1: Do[Stage1Result] = ???  
def stage2(result1: Stage1Result): Do[Stage2Result] = ???  
  
val flatMapped: Do[Stage2Result] = stage1.flatMap(stage2)
```



MONADIC GATED NET

```
type Stage1Result = (Tape[Double, Double], Tape[Double, Double])
def monadicGatedNet(input: Input): Output = {
  val condition = gate(input)
  val stage1: Do[Stage1Result] = (condition._1.forward) tuple2 (condition._2.forward)
  def stage2(pair: Stage1Result) = {
    if (pair._1.data > pair._2.data) {
      (condition._1 * leftSubnet(input)).forward
    } else {
      (condition._2 * rightSubnet(input)).forward
    }
  }
}

val gatedForward = stage1.flatMap(stage2)
INDArrayLayer(gatedForward)
}
```

MONADIC GATED NET

```
class Do[A] {  
  def tuple2[B](fb: Do[B]): Do[(A, B)]  
}
```

MONADIC GATED NET

```
type Stage1Result = (Tape[Double, Double], Tape[Double, Double])
def monadicGatedNet(input: Input): Output = {
  val condition = gate(input)
  val stage1: Do[Stage1Result] = (condition._1.forward) tuple2 (condition._2.forward)
  def stage2(pair: Stage1Result) = {
    if (pair._1.data > pair._2.data) {
      (condition._1 * leftSubnet(input)).forward
    } else {
      (condition._2 * rightSubnet(input)).forward
    }
  }

  val gatedForward = stage1.flatMap(stage2)
  INDArrayLayer(gatedForward)
}
```

PARALLEL GATED NET

```
val stage1 = (condition._1.forward) tuple2 (condition._2.forward)
```

PARALLEL GATED NET

~~val state1 = (condition1.forward) tuple2 (condition2.forward)~~

PARALLEL GATED NET

~~`val stage1 = (condition._1.forward) tuple2 (condition._2.forward)`~~

`val Parallel(stage1) = Parallel(condition._1.forward) tuple2 Parallel(condition._2.forward)`

PARALLEL GATED NET

```
type Stage1Result = (Tape[Double, Double], Tape[Double, Double])
def monadicGatedNet(input: Input): Output = {
  val condition = gate(input)
  val Parallel(stage1) = Parallel(condition._1.forward) tuple2 Parallel(condition._2.forward)

  def stage2(pair: Stage1Result) = {
    if (pair._1.data > pair._2.data) {
      (condition._1 * leftSubnet(input)).forward
    } else {
      (condition._2 * rightSubnet(input)).forward
    }
  }

  val gatedForward = stage1.flatMap(stage2)
  INDArrayLayer(gatedForward)
}
```