

Self driving infrastructure

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Topics

- Cluster management systems
- Today's problems with operating cluster management systems
- A self-driving approach



Motivation: microservices

Increased operational cost

 a lot of components
 dynamic dependencies
 fast deployment iteration

 Solution: automation





Cluster management system

Automation

 Scheduling
 Deployment
 Healing
 Discovery/load balancing
 Scaling







Scheduling





Scheduling





Discovery







Discovery

color=yellow Select color = yellow





Load balancing

yellow.mycluster Select color = yellow



5

Healing

Controller manager





5

Healing

Controller manager





5

Healing

Controller manager





People love automation kubernetes





kubernetes













I hate Kubernetes!



I hate to OPERATE Kubernetes!



Kubernetes Architecture



Operating Kubernetes

- Installation
- Upgrade
- Healing
- Scaling
- Security

. . .

• Monitoring

Installation

- SSH

- Install kubelet
 - \$pkgmanager install kubelet
- Install container runtime
 - \$pkgmanager install [docker|rkt]
- Start kubelet
 - Systemctl start kubelet

Installation - master

- SSH
- Install scheduler
- Install controller manager
- Install API server
- Config them correctly
- Start them

Installation - etcd

- SSH
- Install etcd
- Config them correctly
- Start them

Installation

Upgrade

- SSH
- Upgrade container runtime
- Upgrade Kubelet

Upgrade - master

- SSH
- Upgrade master components

Upgrade - etcd

- SSH
- Upgrade etcd

Upgrade

Rollback

Problems

A lot of manual/semi-manual work No standard way to approach all the problems

do it wrong, lose the cluster!

// gcc source code
#include <stdio.h>
int main()

compile_c(argv[1]);

gcc

gcc

// golang source code
package main
import "os"

func main() {
 compile_go(os.Args[1:])

\$ uname -s
minix
\$ gcc linux.c




\$ uname -s
minix
\$ gcc linux.c











\$ uname -s
linux
\$ gcc linux.c





\$ uname -s
linux
\$ gcc linux.c





Self-hosted Kubernetes?



What is self-hosted Kubernetes?

Kubernetes manages own core components
 Core components deployed as native API objects



Self-hosted k8s Architecture

k8s cluster





Why Self-host Kubernetes?

- Operational expertise around app management in k8s extends to k8s itself
 - E.g. scaling
- Bootstrapping simplified
- Simply cluster life cycle management
 - E.g. updates
- Upstream improvements in Kubernetes directly translate to improvements in managing Kubernetes



Simplify Node Bootstrap

On-host requirements become:
Kubelet
Container Runtime (docker, rkt, ...)



Any Distro Node Bootstrap

• Install kubelet

- \$pkgmanager install kubelet
- Install container runtime
 - \$pkgmanager install [docker|rkt]
- Write kubeconfig
 - scp kubeconfig user@host:/etc/kubernetes/kubeconfig
- Start kubelet
 - Systemctl start kubelet



Simplify k8s lifecycle management

Manage your cluster with only kubectl

Upgrading a self-hosted Kubernetes cluster:

\$ kubectl apply -f kube-apiserver.yaml \$ kubectl apply -f kube-scheduler.yaml \$ kubectl apply -f kube-controller-manager.yaml \$ kubectl apply -f kube-proxy.yaml



Launching a self-hosted cluster

Need an initial control plane to bootstrap a self-hosted cluster

Bootkube:

Acts as a temporary control plane long enough to be replaced by a self-hosted control plane.
Run only on very first node, then not needed again.

github.com/kubernetes-incubator/bootkube



How Bootkube Works































But wait! There's more!

You can even self-host etcd!

<u>https://coreos.com/blog/introducing-the-etcd-operator.html</u> <u>https://github.com/coreos/etcd-operator</u>



How to bootstrap self-hosted etcd















Disaster Recovery

Node failure in HA deployments (Kubernetes)

Partial loss of control plane components (Kubernetes)

Power cycling the entire control plane (Kubernetes)

Permanent loss of control plane (External tool)



Disaster Recovery

Permanent loss of control plane

- Similar situation to initial node bootstrap, but utilizing existing etcd state or etcd backup.
- Need to start a temporary replacement api-server
 Could be binary, static pod, new tool, bootkube, etc.
- Recovery once etcd+api is available can be done via kubectl (as seen previously)



Self-Driving Kubernetes



Self driving

- A self-hosted cluster launched via Bootkube
- Upgraded via Kubernetes APIs and an Operator
- Automated by single-button or fully automatic



G Kubernetes Version Operator



Update status to v1.4.5



The infrastructure

Workload driven

Automation driven

Easy to manage: self driving approach (Today's topic)

Security focused


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Thank you!